

FORM PTO-1390 REV. 5-93		US DEPARTMENT OF COMMERCE PATENT AND TRADEMARK OFFICE	ATTORNEYS DOCKET NUMBER <u>P01.0132</u>
<b>TRANSMITTAL LETTER TO THE UNITED STATES DESIGNATED/ELECTED OFFICE (DO/EO/US) CONCERNING A FILING UNDER 35 U.S.C. 371</b>		U.S. APPLICATION NO. (if known, see 37 CFR 1.5) <u>09/807522</u>	
INTERNATIONAL APPLICATION NO. <b>PCT/EP99/07631</b>	INTERNATIONAL FILING DATE <b>12 October 1999</b>	PRIORITY DATE CLAIMED <b>12 October 1998</b>	
<p><b>TITLE OF INVENTION</b>  <b>"ELECTRONIC CONTROL DEVICE COMPRISING A PARALLEL DATABUS, AND A METHOD FOR OPERATING THE CONTROL DEVICE"</b></p>			
<p><b>APPLICANT(S) FOR DO/EO/US</b>  <b>Hans-Detlef GROEGER and Robert BAUMGARTNER</b></p>			
<p>Applicant herewith submits to the United States Designated/Elected Office (DO/EO/US) the following items and other information:</p> <ol style="list-style-type: none"> <li>1. <input checked="" type="checkbox"/> This is a <b>FIRST</b> submission of items concerning a filing under 35 U.S.C. 371.</li> <li>2. <input type="checkbox"/> This is a <b>SECOND</b> or <b>SUBSEQUENT</b> submission of items concerning a filing under 35 U.S.C. 371.</li> <li>3. <input checked="" type="checkbox"/> This express request to begin national examination procedures (35 U.S.C. 371(f)) at any time rather than delay.</li> <li>4. <input checked="" type="checkbox"/> A proper Demand for International Preliminary Examination was made by the 19th month from the earliest claimed priority date.</li> <li>5. <input checked="" type="checkbox"/> A copy of International Application as filed (35 U.S.C. 371(c)(2))       <ol style="list-style-type: none"> <li>a. <input checked="" type="checkbox"/> is transmitted herewith (required only if not transmitted by the International Bureau).</li> <li>b. <input type="checkbox"/> has been transmitted by the International Bureau.</li> <li>c. <input type="checkbox"/> is not required, as the application was filed in the United States Receiving Office (RO/US)</li> </ol> </li> <li>6. <input checked="" type="checkbox"/> A translation of the International Application into English (35 U.S.C. 371(c)(2)).</li> <li>7. <input checked="" type="checkbox"/> Amendments to the claims of the International Application under PCT Article 19 (35 U.S.C. §371(c)(3))       <ol style="list-style-type: none"> <li>a. <input type="checkbox"/> are transmitted herewith (required only if not transmitted by the International Bureau).</li> <li>b. <input type="checkbox"/> have been transmitted by the International Bureau.</li> <li>c. <input type="checkbox"/> have not been made; however, the time limit for making such amendments has NOT expired.</li> <li>d. <input checked="" type="checkbox"/> have not been made and will not be made.</li> </ol> </li> <li>8. <input checked="" type="checkbox"/> A translation of the amendments to the claims under PCT Article 19 (35 U.S.C. 371(c)(3)).</li> <li>9. <input checked="" type="checkbox"/> An oath or declaration of the inventor(s) (35 U.S.C. 371(c)(4)).</li> <li>10. <input checked="" type="checkbox"/> A translation of the annexes to the International Preliminary Examination Report under PCT Article 36 (35 U.S.C. 371(c)(5)).</li> </ol> <p><b>Items 11. to 16. below concern other document(s) or information included:</b></p> <ol style="list-style-type: none"> <li>11. <input checked="" type="checkbox"/> An Information Disclosure Statement under 37 C.F.R. 1.97 and 1.98; (<b>PTO 1449, Prior Art, Search Report</b>).</li> <li>12. <input checked="" type="checkbox"/> An assignment document for recording. A separate cover sheet in compliance with 37 C.F.R. 3.28 and 3.31 is included. <b>(SEE ATTACHED ENVELOPE)</b></li> <li>13. <input checked="" type="checkbox"/> A <b>FIRST</b> preliminary amendment. <input type="checkbox"/> A <b>SECOND</b> or <b>SUBSEQUENT</b> preliminary amendment.</li> <li>14. <input checked="" type="checkbox"/> A substitute specification &amp; marked up version of application.</li> <li>15. <input type="checkbox"/> A change of power of attorney and/or address letter.</li> <li>16. <input checked="" type="checkbox"/> Other items or information:       <ol style="list-style-type: none"> <li>a. <input checked="" type="checkbox"/> Submittal of Drawings</li> <li>b. <input checked="" type="checkbox"/> EXPRESS MAIL #EL 843728455US, dated April 12, 2001.</li> </ol> </li> </ol>			

U.S.APPLICATION NO. (if known. See 37 C.F.R. 1.5)		INTERNATIONAL APPLICATION NO. PCT/EP99/07631	ATTORNEY'S DOCKET NUMBER P01,0132
17. <input checked="" type="checkbox"/> The following fees are submitted:		CALCULATIONS	PTO USE ONLY
<b>BASIC NATIONAL FEE (37 C.F.R. 1.492(a)(1)-(5):</b>			
Search Report has been prepared by the EPO or JPO ..... \$860.00			
International preliminary examination fee paid to USPTO (37 C.F.R. 1.482) .. \$700.00			
No international preliminary examination fee paid to USPTO (37 C.F.R. 1.482) but international search fee paid to USPTO (37 C.F.R. 1.445(a)(2) ..... \$770.00			
Neither international preliminary examination fee (37 C.F.R. 1.482) nor international search fee (37 C.F.R. 1.445(a)(2) paid to USPTO ..... \$1040.00			
International preliminary examination fee paid to USPTO (37 C.F.R. 1.482) and all claims satisfied provisions of PCT Article 33(2)-(4) ..... \$ 96.00			
<b>ENTER APPROPRIATE BASIC FEE AMOUNT =</b>		\$ 860.00	
Surcharge of \$130.00 for furnishing the oath or declaration later than <input type="checkbox"/> 20 <input type="checkbox"/> 30 months from the earliest claimed priority date (37 C.F.R. 1.492(e)).		\$	
Claims	Number Filed	Number Extra	Rate
Total Claims	14 - 20 =		X \$ 18.00 \$
Independent Claims	3 - 3 =		X \$ 80.00 \$
Multiple Dependent Claims		\$270.00 + \$	
<b>TOTAL OF ABOVE CALCULATIONS =</b>		\$ 860.00	
Reduction by 1/2 for filing by small entity, if applicable. Verified Small Entity statement must also be filed. (Note 37 C.F.R. 1.9, 1.27, 1.28)		\$	
<b>SUBTOTAL =</b>		\$ 860.00	
Processing fee of \$130.00 for furnishing the English translation later than <input type="checkbox"/> 20 <input type="checkbox"/> 30 months from the earliest claimed priority date (37 CFR 1.492(f)).		\$ +	
<b>TOTAL NATIONAL FEE =</b>		\$ 860.00	
Fee for recording the enclosed assignment (37 C.F.R. 1.21(h). The assignment must be accompanied by an appropriate cover sheet (37 C.F.R. 3.28, 3.31). \$40.00 per property		\$ +	
<b>TOTAL FEES ENCLOSED =</b>		\$ 860.00	
		Amount to be refunded	\$
		charged	\$
a. <input checked="" type="checkbox"/> A check in the amount of \$ <u>860.00</u> to cover the above fees is enclosed.			
b. <input type="checkbox"/> Please charge my Deposit Account No. _____ in the amount of \$ _____ to cover the above fees. A duplicate copy of this sheet is enclosed.			
c. <input checked="" type="checkbox"/> The Commissioner is hereby authorized to charge any additional fees which may be required, or credit any overpayment to Deposit Account No. <u>501519</u> . A duplicate copy of this sheet is enclosed.			
NOTE: Where an appropriate time limit under 37 C.F.R. 1.494 or 1.495 has not been met, a petition to revive (37 C.F.R. 1.137(a) or (b)) must be filed and granted to restore the application to pending status.			
SEND ALL CORRESPONDENCE TO:			
 <b>SIGNATURE</b> <u>Melvin A. Robinson</u> NAME			
<u>31,870</u> Registration Number			
CUSTOMER NO. 26574			

09/807522

JC05 Rec'd PCT/PTO 12 APR 2001

CERTIFICATE OF MAILING

"Express Mail" Mailing Label Number **EL 843728455 US**

Date of Deposit: April 12, 2001

I hereby certify that this correspondence is being deposited with the United States Postal "Express Mail Post Office to Addressee" service under 37 CFR 1.10 on the date indicated above and is addressed to:

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Case Number: P01,0132

Hans-Detlef GROEGER et al.

ELECTRONIC CONTROL DEVICE COMPRISING A PARALLEL DATABUS, AND A METHOD FOR OPERATING THE CONTROL DEVICE

Signature of person mailing documents and fee

P. Hernandez

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-1-

IN THE UNITED STATES ELECTED OFFICE  
OF THE UNITED STATES PATENT AND TRADEMARK OFFICE  
UNDER THE PATENT COOPERATION TREATY-CHAPTER II

**"PRELIMINARY AMENDMENT"**

5 APPLICANT: Hans-Detlef GROEGER et al.

SERIAL NO.: EXAMINER:

FILING DATE: ART UNIT:

INTERNATIONAL APPLICATION NO.: PCT/EP99/07631

INTERNATIONAL FILING DATE: 12 October 1999

10 INVENTION: ELECTRONIC CONTROL DEVICE COMPRISING A  
PARALLEL DATABUS, AND A METHOD FOR  
OPERATING THE CONTROL DEVICE

Hon. Assistant Commissioner for Patents

Box PCT

15 Washington D.C. 20231

SIR:

Amend the above-identified international application before entry into the national stage before the U.S. Patent & Trademark Office under 35 U.S.C. §371 as follows:

20 **IN THE SPECIFICATION**

Amend the specification as follows:

S P E C I F I C A T I O N

TITLE

ELECTRONIC CONTROL DEVICE WITH A PARALLEL DATABUS AND A  
METHOD FOR THE OPERATION OF THE CONTROL DEVICE

BACKGROUND OF THE INVENTION

Field of the Invention

5       The present invention is directed to a control device with a parallel databus  
and to a method for the operation of the control device.

The invention is particularly directed to an electronic control device that  
must process a large data stream such as, for example, a control device for editing  
print data for a high-performance printer.

10     Description of the Related Art

A control device called an "SRA controller" (SRA: Scalable Raster  
Architecture) is described in the publication "Das Druckbuch -- Technik und  
Technologie der Hochleistungsdrucker von Océ Printing Systems GmbH --  
Drucktechnologien", Edition 3c, May 1998, ISBN 3-00-001019-X.

15     The structure of this known control device is schematically shown in  
Figure 1. Such a control device 1 comprises an I/O module 2, one or more raster  
modules 3 and a serializer module 4. The individual modules 2 through 4 are  
connected to one another via a parallel databus 5. The raster modules 3 and the  
serializer module 4 are connected to one another via a further pixel bus 6. A high-  
20     performance printer 7 is connected to the serializer module 4.

The I/O module receives the print information from a computer device that can be a large computer system or a computer network as well. The print information is forwarded from the I/O module 2 to the raster modules 3 and the serializer module 4, whereby the raster modules 3 receive the print image  
5 information and convert it into a print image data stream that can be processed by the high-performance printer 7. These print image data streams are transmitted from the raster modules 3 via the pixel bus 6 to the serializer module 4, which forwards the data streams queued in a specific sequence and to the high-performance printer 7.

10 For example, the databus is a Multibus II (Multibus is a registered trademark of Intel Corp.). The Multibus II is a synchronized bus that is defined in IEEE Standard for a High-Performance Synchronous 32-Bit Bus: MULTIBUS II, The Institute of Electrical and Electronics Engineers, Inc., 345 East 47th Street, NY 10017, USA, 1988. Below, the "MULTIBUS II" is simply referred to as  
15 "multibus".

The modules 2 through 4 of the control device 1 are respectively provided with a processor. An inter-processor communication ensues with a message transfer given systems based on the multibus, whereby messages with data packets having a predetermined length are communicated for the transfer of data.

20 There are two kinds of these messages given the multibus, namely what

are referred to as unsolicited messages and solicited messages. The unsolicited messages can be viewed as "intelligent interrupts", whereby up to 255 interrupt sources (the number of valid addresses) can send an unsolicited message. 28 bytes of status information can be transmitted with an unsolicited message.

5       The properties of an unsolicited message are that their arrival cannot be predicted by the receiver, whereby the transmission modalities (transmission rate, data quantity, ...) are first negotiated with unsolicited messages (buffer request message, buffer grant message and buffer reject message).

A data transfer from the I/O module 2 to the raster modules 3 via the  
10 databus 5 is shown in a flowchart in Figure 2. The actions that occur at the I/O module are thereby shown at the left side, and the actions that are executed at the raster module 3 are shown at the right side.

In step S1, the I/O module 2 sends a message to the raster module 3 that data are present. This message is generated by the processor of the I/O module. In  
15 response thereto, the raster module sends a corresponding message in step S2 if it needs data. This message is triggered by the processor of the raster module 2. When the I/O module 2 has received this message, the processor programs a DMA controller of the I/O module to send the requested data to the raster module and sends a buffer request message to the raster module (step S3). When the  
20 raster module can accept these data, its processor programs a DMA controller for

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the reception of the data and sends a buffer grant message to the I/O module (step S4).

The "negotiations" are ended with the reception of the buffer grant message by the I/O module, and the I/O module sends a data message containing a data packet to the raster module (step S5). Such a data message is transmitted until all data have been communicated to the raster module, whereby this is checked in a step S6.

When all data have been sent to the raster module, then the data transfer is ended (S7).

10 The steps S2 through S6 form a solicited message (broken-line frame), whereby the negotiation (S2 through S4) with which the data are requested is implemented with unsolicited messages. The individual messages of the steps S2 through S4 are respectively generated by the processors of the modules 2, 3.

The above-described interprocessor communication with a message transfer is described under the heading "Message Passing" in the publication by F. Mayer et al., "Message Passing-Protokolle in einem verteilten heterogenen Multibus-II-Mehrrechnersystem" Automatisierungstechnische Praxis -- ATP DE, Oldenburg Verlag, Munich, Volume 37, No. 12, pages 42-44, 46-50, XP000542307, ISSN: 0178-2320.

and data bank system for storing documents in the form of image data that comprises a memory processor unit connected to a databus that works according to the Multibus II protocol and, accordingly, implements the above-described method steps S1 through S7 in the data transfer. This memory processor unit is provided with an ADMA controller that, following the negotiation phase (steps S2 through S4), automatically implements the transmission of the messages (steps S5 and S6).

What are referred to as DMA controllers are known for controlling the read-in and output of memory signals. Their typical structure and functioning are described, for example, in the publication by Tietze, Schenk, "Halbleiter-Schaltungstechnik", Springer-Verlag (1985), pages 672-675. Typical applications and functions of DMA controllers are cited in the publication by Messmer, "PC-hardware", Addison-Wesley, 3rd Edition (1995), pages 515-516.

German Patent Document DE-T2-38 52 378 discloses a mechanism and a  
method for opposite flow control in a bus system, whereby the bus system is  
controlled with a bus administrator. In this known bus system, specific bus  
messages are employed in order to inform a process executing on a bus unit about  
a result or about an unanticipated input of another bus unit. The bus unit that  
receives the message knows immediately to where the message must be  
forwarded, instead of having to derive where the message is to be forwarded from

the sender. The uninterrupted process need not return to the sender of the message in order to determine what is to be done. Since this message contains a report about what is to be done, little time is wasted determining the reason for sending the message.

5        A plurality of bus units can thus quickly addressed with this bus system and their processing status can be immediately modified.

#### SUMMARY OF THE INVENTION

The present invention provides a control device that comprises a parallel databus and a plurality of assemblies respectively provided with a processor that  
10      can communicate over the databus such that a large data stream can be more quickly and efficiently processed. The invention also provides a method for operating such a control device with which a large data stream can be simply and efficiently governed in the control device.

In particular, the invention provides an electronic control device with a  
15      parallel databus and a plurality of assemblies connected to the databus that respectively include a processor, a memory device and a DMA controller and that are connected to the databus with a bus controller, data is transmitted between a transmitter assembly and a receiver assembly with messages, the bus controller of the transmitter assembly is fashioned such that, in response to a request message  
20      of the receiver assembly, it programs the DMA controller to read out data stored

in the memory device of the transmitter assembly and to send them to the receiver assembly, without making use of the processor of the transmitter assembly.

In a preferred embodiment, the DMA controller is integrated into the bus controller of the transmitter assembly. The databus of one example is a data bus compatible with the MULTIBUS II. The receiver assembly may be a fail-safe counter for monitoring the message transfer that is restarted upon reception of a data message.

The present invention also provides a method for operating an electronic device, where the electronic control device includes a parallel databus and a plurality of assemblies connected to the databus that are respectively provided with a processor and a memory device and are connected to the databus with a bus controller, whereby data are transmitted between a transmitter assembly and a receiver assembly with messages, and the receiver assembly initiates a data transfer by sending a request message to the transmitter module, and the bus controller of the transmitter assembly, without making use of the processor of the transmitter assembly, transmits data stored in the memory device of the transmitter assembly to the receiver assembly in response to the request message.

Preferably, a control device as set forth in the foregoing is employed. In one embodiment, following the reception of a request message, the bus controller of the transmitter assembly sends a plurality of data messages respectively

containing a data packet to the receiver assembly. For example, information for programming a DMA controller arranged at the transmitter assembly for reading and sending the data stored in the memory device of the transmitter assembly are transmitted with the request message. A DMA controller arranged on the transmitter assembly may be programmed by the bus controller on the basis of data communicated with the request message, being program to read and transmit the data stored in the memory device of the transmitter assembly. The DMA controller arranged on the receiver assembly is programmed for the reception of the data with the transmission of the request message. In one embodiment, the data are transmitted with a plurality of messages that respectively contain a data packet. The transmitter assembly may include a buffer wherein an entry is provided for each assembly present in the control device, so that the parameters characterizing the data transfer are written into the respectively entry and stored during a data transfer and are erased after the conclusion of the data transfer.

Specifically, upon reception of a request message, the bus controller of the transmitter assembly checks whether the entry of the buffer allocated to the assembly sending the request message is already written with data characterizing a data transfer in order to prevent two data transfers from being simultaneously initiated with the same receiver assembly.

The invention also provides a control device for editing print data for a

high-performance printer, with the features set forth above whereby the transmitter assembly forms an I/O module and a plurality of receiver modules that respectively form a raster module are provided.

The inventive electronic control device is provided with a parallel databus  
5 and a plurality of assemblies connected to the databus that respectively comprise a processor and a memory device and are connected to the databus bus with a bus controller, whereby data are transmitted between a transmitter assembly and a receiver assembly with messages. The invention is characterized in that the bus controller of the transmitter assembly is fashioned such that, without making use  
10 of the processor of the transmitter assembly, it reads data stored in the memory device of the transmitter assembly in response to a request message of the receiver assembly and transmits them to the receiver assembly. The receiver assembly thus triggers an automatic transmission of the data at the transmitter assembly on the basis of its request message. This leads to a considerable unburdening of the  
15 transmitter assembly since the data can be directly read with a DMA controller significantly faster and more efficiently, and the processor is not occupied long by such a data transmission. Moreover, the initially described "negotiation", which comprises three message transmissions given the traditional multibus (see Figure 2), is reduced to the transmission of a single request message, as a result whereof  
20 a further simplification and acceleration of the transmission procedure is achieved.

- The method for the operation of such an electronic control device is characterized in that the receiver assembly initiates a data transfer by sending the request message to the transmitter assembly, and the bus controller of the transmitter assembly, without making use of the processor of the transmitter assembly, reads data stored in the memory device of the transmitter assembly in response to the request message and transmits them to the receiver assembly. As a result thereof, a large data stream can be quickly and efficiently transmitted from the transmitter assembly to the receiver assembly, so that the control device can govern a large data stream.
- In a preferred embodiment of the invention, the data needed for programming a DMA controller arranged on the transmitter assembly are communicated from the receiver assembly to the transmitter assembly by means of the request message. With the request message, thus, the receiver assembly controls the data transmission from the transmitter assembly.
- With the inventive method, the individual receiver assemblies can independently and simultaneously fetch the data they want from the transmitter assembly. As a result of the automatic processing of the request messages in the transmitter assembly, this can make the data available very fast. The simplification of the transmission protocol effects a further speed-up of the transmission procedure.

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## BRIEF DESCRIPTION OF THE DRAWINGS

The invention is explained in greater detail below on the basis of an exemplary embodiment shown in the drawings.

Figure 1 shows the fundamental structure of a control device for editing  
5 print data for a high-performance printer in a block circuit diagram;

Figure 2 is a flowchart of a data transfer according to a transmission  
method known from the multibus;

Figure 3 is a block diagram showing two assemblies connected via a  
databus;

10 Figure 4 shows the inventive data transfer in a flowchart;

Figure 5 shows the structure of a request message in a block circuit  
diagram;

Figure 6 shows the structure of a data message in a block circuit diagram;  
and

15 Figure 7 shows the structure of an entry in a buffer provided at the  
transmitter assembly in a block circuit diagram.

## DETAILED DESCRIPTION OF THE PREFERRED EMBODIMENTS

The present invention is explained on the basis of an exemplary  
embodiment of an electronic control device 1 for controlling a high-performance  
20 printer that has the same structure as the known control device shown in Figure 1

and that is provided with an I/O module 2, one or more raster modules 3 and a serializer module 4. The individual modules 2 through 4 are connected to one another via a parallel databus 5. The raster modules 3 and the serializer module 4 are connected to one another via a further pixel bus 6. The high-performance printer 7 is connected to the serializer module 4.

The databus 5 is a development of the multibus and is essentially compatible therewith.

The modules 2 through 4 respectively represent an assembly 8 connected to the databus. Two such assemblies 8, namely the I/O module 2 and the raster module 3, are schematically shown in Figure 3.

The assemblies 8 respectively comprise a bus controller 9 that are each provided with an internal DMA controller 10 integrated into the bus controller 9. The assemblies respectively have a processor 11 and memory devices 12 that are connected to one another and to the bus controller 9 with an internal computer bus 13. The assemblies 8 comprise further elements such as, for example, components and lines for further interfaces and the like that, however, are not shown in Figure 3 for reasons of simplification.

The inventive, automatic requested message transfer is explained below on the basis of the flowchart shown in Figure 4. The actions that occur at the I/O module 2 are thereby again shown at the left aside, and the actions that are

implemented at the raster module 3 are shown at the right side.

During the step S1, the I/O module 2 sends a message to a raster module 3 that data are present. This message is generated by the processor of the I/O module and corresponds to the step Si according to the known method shown in  
5 Figure 2.

In response thereto, the raster module 3 checks in a step S8 whether it needs the data offered by the I/O module 2 and whether there is enough memory space for the acceptance of the data. This check is carried out by the processor 11 of the raster module 3.

When these data are not present, the processor 11 -- in a step S9 -- programs the DMA controller 10 in the bus controller 9 for the reception of a data packet and write a data request message into the bus controller 9. The data request message contains the address of the data in the memory of the I/o module 2, the plurality of data bytes that are to be transmitted, and what is referred to as a  
10 duty cycle for the transmission of the requested messages. The duty cycle defines the spacing in which the requested messages are sent via the data bus 5. Over and above this, further data can also be contained in the data request message that define the respective data transfer in greater detail. The structure of this data request message is shown in Figure 5. The data request message represents an  
15 unsolicited message. The message type has the value 02H.  
20

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During the step S10, the bus controller 9 of the raster module 3 sends this data request message to the I/O module 2 via the databus 5.

Based on the criterion of the data (address of the data in the memory of the I/O module, plurality of data bytes, duty cycle, etc.) contained in the data request 5 message, the bus controller 9 of the I/O module 2 programs its DMA controller 10 with the address and the number of bytes of a data message to be transmitted (step S11).

The structure of such a data message is shown in Figure 6. A data message comprises a source address and a destination address, whereby the 10 occupancy of the data request message is valid therefor, so that the source address is the address of the receiver assembly and the destination address is the address of the transmitter assembly. Two types of data message are provided, namely the type 3CH and the type 3DH, whose significance shall be explained later. A data packet with 32 bytes (byte 0 through byte 31) can be transmitted with the data 15 message shown in Figure 6.

For sending the data message shown in Figure 6, the bus controller starts the DMA controller 10 in step S12 and packs the data communicated from the DMA controller 10 to the bus controller 9 into a data packet. The data packet is transmitted from the I/O module 2 to the raster module 3 with a data message via 20 the databus 5.

A check is carried out in step S13 as to whether all data have already been transmitted. When further data have to be transmitted, then the program runs returns to the step S12, as a result whereof the next data message is transmitted. This procedure is repeated until all data have been transmitted in packets from the 5 I/O module to the raster module. All of the data messages except the last data message that are thereby employed are of the type 3CH. The last data message is of the type 3DH. The data transfer has been ended with the transmission of all data packets (step S14). Due to the reception of the data message of the type 3DH, an interrupt is triggered at the raster module 3 that indicates to the processor 10 of the raster module 3 that the requested data transfer has been ended. A message to the processor of the I/O module 2 only ensues when an error has occurred in the transmission of the data.

The steps S8 through S14 forms the automatic requested message transfer (broken-line frame). This automatically requested message transfer comprises 15 only one unsolicited message, namely the data request message of the step S10, and the solicited data messages of the step S14. Compared to the solicited messages of the known multibus, the number of unsolicited messages is reduced from 3 th 1. A significant unburdening at the databus 5 is thereby achieved.

A defined data quantity of, for example, 4 KB is transmitted with such an 20 automatic requested message transfer.

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A buffer is provided in the bus controller 9 of the I/O module 2 wherein the parameters of the automatically requested message transfers can be deposited. One entry is provided in this buffer for each assembly 8 that can function as receiver assembly 3. In the present exemplary embodiment, the buffer comprises 5 21 entries. The parameters contained in the entries are (Figure 7):

1. source and destination address for the automatic requested message transfer,
2. duty cycle for the data packets,
3. DMA address of the data in the memory device, and
- 10 4. plurality of data bytes.

Upon reception of a request message, the bus controller 9 of the I/O module can check whether the entry of the buffer allocated to the raster module 3 sending the request message is already described with data characterizing a data transfer. When the data of another automatically requested message transfer are 15 already contained in the entry, an error message can be output and the request message can be rejected in order to prevent two message transfers from being simultaneously initiated with the same raster module.

The bus controller 9 sees to it that the request messages are processed in the sequence of their arrival. This assures that each raster module has a turn.

20 Given an occupied entry in the buffer or given an occupied input buffer

wherein the arriving messages are intermediately stored, the request message is rejected with the error message NACK. The request message is subsequently repeated until it can either be processed or the number of repetitions defined in the protocol has been reached. When the data messages cannot be received by the raster module 3, the error NACK is also output and they are repeated until they can be accepted or until the defined plurality of repetitions has been reached.

5

When a raster module has initiated an automatic requested message transfer and sends further data request messages during its own transfer, then these messages are not transmitted. Instead, a transmit error is reported. Upon 10 readout of the rejected unsolicited message from an error FIFO known by the multibus, a "no resource" bit is set.

When a DMA error occurs during the reception of the data at the raster module 3, then a corresponding status bit is set in the DMA controller 10 of the bus controller 9 and the DMA controller ends the transfer on its own. When no 15 immediate actions are triggered at the processor as a result thereof, then the following executive sequence derives:

An internal buffer of the raster module 3 for the reception of the data messages fills up. The raster module therefore rejects further data messages. The bus controller of the I/O module repeats a rejected data message for a maximum 20 of 127 times and then ends the data transfer on its own. The bus controller 9 of

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the I/O module subsequently reports the situation to its processor.

In addition, an internal fail-safe counter runs down at the raster module, this being always set to its start value by the reception of a data message. The rundown of the counter is communicated to the processor of the raster module,  
5 which subsequently implements an error recovery known from the multibus.

In a preferred embodiment of the invention for accelerating the above executive sequence at the side of the raster module (the fail-safe counter runs down in approximately 2 seconds), the processor of the raster module can already react to the DMA error in that it stops the DMA reception channel of the transfer  
10 and communicates the end of the transfer via an unsolicited message to the I/O module. The stopping ensues at the I/O module by an erase instruction output by the bus controller to erase the corresponding DMA reception channel.

When a DMA error occurs at the I/O module, the DMA channel is stopped by the internal executive sequencer -- as in the case of an error at the raster  
15 module -- and the corresponding status bits are set. Additionally, an unsolicited message is sent to the raster module, so that this stops the reception of the data message. Due to this message, the processor of the raster module forwards a stop instruction to the DMA controller and an erase instruction to the reception channel of the automatically requested message transfer. When the processor of the I/O  
20 module does not react to the DMA error, then the aforementioned fail-safe counter

on the raster module runs down. Subsequently, the processor of the raster module must send an unsolicited message to the I/O module, so that the I/O module also ends the transfer.

The aforementioned fail-safe counter of the raster module is provided for  
5 the reception of the data messages and is restarted every time after the reception  
of a data message of the type 3CH. It runs down when no further data message is  
received within the time that has been set. In this case, the processor of the raster  
module stops the DMA channel in the bus controller and the reception channel of  
the automatically requested message transfer is erased. Additionally, an  
10 unsolicited message is sent to the I/O module so that the I/O module can stop the  
automatic requested message transfer. A stop instruction for the DMA channel of  
the I/o module is thereby not necessary since this is undertaken by the internal  
executive sequences of the bus controller.

A running, automatic requested message transfer at the raster module can  
15 be aborted with an erase instruction at the corresponding reception channel. The  
instruction takes immediate effect. All data messages arriving thereafter are  
rejected by the bus controller with an error message "transfer not understood" that  
is known from the multibus. The termination of the reception channel of the  
DMA controller must likewise be implemented by the processor.

20 A running, automatic requested message transfer is aborted or,

respectively, arrested at the I/o module as a result of the following actions:

a) An error has occurred at the databus. All errors come into consideration:

- The repetition rate for a data message has reached the maximum value.
- 5            • a bus error, bus timeout or an agent error occurred in the transmission of the data message.

b) An error occurred in the DMA transmission. The following errors come into consideration:

- parity error
- 10            • page miss error
- fatal error given a transfer via the internal computer bus (PCI bus).

c) The processor aborts the running, automatic requested message transfer with a command.

In cases a) and b), the automatic, requested message transfer is aborted by 15 the internal controller of the bus controller due to the error. The internal controller reports the cause of the error by setting an ASOMERR bit in a message status register. When a corresponding interrupt is enabled in a message control register, then an interrupt is additionally generated. The processor of the I/O module can determine the cause of the error by reading out an ASOM status 20 register allocated to the automatic, requested message transfer. Before an

automatic, requested message transfer can be resumed, the processor of the I/O module must output a corresponding command (ASOMGO).

The processor cannot abort an running, automatic requested message transfer at any time (see c). Dependent on the command employed, the automatic 5 requested message transfer is still completely implemented or is immediately interrupted. It must be taken into consideration in the latter case that the raster module is waiting for the further arrival of data messages. A corresponding message is therefore sent from the I/O module to the raster module given an interruption of an automatically requested message transfer.

10 For logging the automatic requested message transfer, the following options can be established at the I/O module:

1. Each automatic requested message transfer is forwarded to the processor of the I/O module. Which assembly requested an automatic requested message transfer can thus be kept track of on the I/O module.
- 15 2. A register is provided in the bus controller that contains the message ID of the assembly requesting the automatic requested message transfer. This register is set to the message ID at the beginning of the transfer and is in turn reset at the end. The register can be read out at any time by the processor.

20 The invention has been set forth above on the basis of a control device for

editing print data for a high-performance printer. The inventive control device is equally suited for any application wherein a large data stream must be processed. The I/O module, accordingly, can be considered in general as a transmitter assembly and the raster module can be considered as a receiver module, whereby  
5 the data are transmitted from the transmitter module to the receiver module.

In the above-described exemplary embodiment, a databus is employed that is essentially compatible with the multibus. The invention, however, is not limited to this type of databus but can be designed for any parallel databus that is suitable for a multi-processor architecture.

10 A DMA controller 10 integrated into the bus controller 9 is provided in the assemblies recited in the exemplary embodiment.

In the framework of the invention, of course, the DMA controller 10 can also be arranged outside the bus controller 9 on the assembly.

The above-described data messages respectively transmit a data packet of  
15 32 bytes. The size of these data packets can be varied as needed and, for example, comprise 64 or 128 bytes. The data quantity transferred with an automatic requested message transfer can be fixed to any desired size of, for example, 4 KB, 8 KB, 16 KB or the like.

The invention can be summarized in brief in the following way:  
20 It is directed to an electronic control device with a parallel databus and a plurality

of assemblies connected to the databus. The assemblies respectively comprise a processor and a memory device and are connected to the databus with a bus controller. The data are transmitted between a transmitter assembly and a receiver assembly with messages. The data bus essentially corresponds to the

5       MULTIBUS II.

The invention is characterized in that the bus controller of the transmitter assembly is fashioned such that, without making use of the processor of the transmitter assembly, it reads data stored in the memory device of the transmitter assembly in response to a request message of the receiver assembly and sends them to the receiver assembly.

10      As a result thereof, first, the processor of the transmitter assembly (I/O module) is relieved and, second, the communication between the transmitter assembly and the receiver assembly (raster module) can be significantly lowered and reduced to a single request message in the negotiation or, respectively, 15     determination of the data transfer. The electronic control device is preferably fashioned for a control device for driving a high-performance printer.

20      Although other modifications and changes may be suggested by those skilled in the art, it is the intention of the inventors to embody within the patent warranted hereon all changes and modifications as reasonably and properly come within the scope of their contribution to the art.

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**IN THE CLAIMS**

We claim:

- 1.(Amended) An electronic control device, comprising:
  - a parallel databus;
  - 5 a plurality of assemblies connected to said parallel databus, said plurality of assemblies each including:
    - a processor,
    - a memory device;
    - 10 a DMA controller;
  - 10 a bus controller connecting said plurality of assemblies to said parallel databus such that data are transmitted between a transmitter assembly of said plurality of assemblies and a receiver assembly of said plurality of assemblies with messages, the bus controller of the transmitter assembly being fashioned such that the transmitter assembly programs the DMA controller to read out data stored in the memory device of the transmitter assembly and to send them to the receiver assembly in response to a request message of the receiver assembly without making use of the processor of the transmitter assembly.
- 2.(Amended) An electronic control device according to claim 1, wherein

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the DMA controller is integrated into the bus controller of the transmitter assembly.

3.(Amended) An electronic control device according to claim 1, wherein the databus is a data bus compatible with MULTIBUS II.

5       4. (Amended) An electronic control device according to claim 1, wherein the receiver assembly includes a fail-safe counter for monitoring message transfer that is restarted upon reception of a data message.

10      5.(Amended) A method for operating an electronic device, the electronic control device including a parallel databus and a plurality of assemblies connected to the databus that are respectively provided with a processor and a memory device and are connected to the databus with a bus controller, comprising the steps of:

transmitting data between a transmitter assembly and a receiver assembly with messages;

15      initiating a data transfer by sending a request message from the receiver assembly to the transmitter module; and

transmitting data stored in the memory device of the transmitter assembly to the

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receiver assembly in response to the request message without making use of the processor of the transmitter assembly from the bus controller of the transmitter assembly.

6. (Amended) A method according to claim 5, further comprising the step

5 of:

utilizing a control device having

a parallel databus;

a plurality of assemblies connected to said parallel databus, said plurality of assemblies each including:

10 a processor,

a memory device;

a DMA controller;

a bus controller connecting said plurality of assemblies to said parallel

databus such that data are transmitted between a transmitter

15 assembly of said plurality of assemblies and a receiver assembly of said plurality of assemblies with messages, the bus controller of the transmitter assembly being fashioned such that the transmitter assembly programs the DMA controller to read out data stored in the memory device of the transmitter assembly and to send them to

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the receiver assembly in response to a request message of the  
receiver assembly without making use of the processor of the  
transmitter assembly.

7. (Amended) A method according to claim 5, further comprising the step

5 of:

sending a plurality of data messages respectively containing a data packet to the  
receiver assembly from the bus controller of the transmitter assembly  
following reception of a request message.

8. (Amended) A method according to claim 5, further comprising the step

10 of:

transmitting information for programming a DMA controller arranged at the  
transmitter assembly for reading and sending the data stored in the  
memory device of the transmitter assembly with the request message .

9. (Amended) A method according to claim 5, further comprising the step

15 of:

programming a DMA controller arranged on the transmitter assembly by the bus  
controller on a basis of data communicated with the request message,

being programmed to read and transmit the data stored in the memory device of the transmitter assembly.

10. (Amended) A method according to claim 5, further comprising the steps of:

5 programming a DMA controller arranged on the receiver assembly for reception of the data with the transmission of the request message.

11. (Amended) A method according to claim 5, further comprising the step of:

transmitting the data with a plurality of messages that respectively contain a data  
10 packet.

12. (Amended) A method according to claim 5, further comprising the step of:

providing an entry in a buffer of the transmitter is provided for each assembly  
present in the control device, so that the parameters characterizing the data  
15 transfer are written into the respectively entry and stored during a data transfer and are erased after the conclusion of the data transfer.

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13. (Amended) A method according to claim 12,  
upon reception of a request message, checking by the bus controller of the  
transmitter assembly whether the entry of the buffer allocated to the  
assembly sending the request message is already written with data  
5 characterizing a data transfer in order to prevent two data transfers from  
being simultaneously initiated with the same receiver assembly.
14. (Amended) A control device for editing print data for a high-  
performance printer, comprising;  
a parallel databus;  
10 a plurality of assemblies connected to said parallel databus, said plurality of  
assemblies each including:  
a processor,  
a memory device;  
a DMA controller;  
15 a bus controller connecting said plurality of assemblies to said parallel databus  
such that data are transmitted between a transmitter assembly of said  
plurality of assemblies and a receiver assembly of said plurality of  
assemblies with messages, the bus controller of the transmitter assembly  
being fashioned such that the transmitter assembly programs the DMA

controller to read out data stored in the memory device of the transmitter assembly and to send them to the receiver assembly in response to a request message of the receiver assembly without making use of the processor of the transmitter assembly the transmitter assembly forming an I/O module and a plurality of receiver modules that respectively form a raster module.

## IN THE ABSTRACT

Add a new abstract as follows:

## ABSTRACT OF THE DISCLOSURE

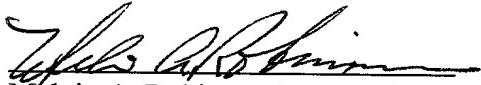
10 An electronic control device with a parallel databus and a plurality of assemblies connected to the databus. The assemblies each include a processor and a memory device and are connected to the databus with a bus controller. The data are transmitted between a transmitter assembly and a receiver assembly with messages. The data bus essentially corresponds to the MULTIBUS II. The bus  
15 controller of the transmitter assembly is fashioned such that, without making use of the processor of the transmitter assembly, it reads data stored in the memory device of the transmitter assembly in response to a request message of the receiver assembly and sends them to the receiver assembly.

**REMARKS**

The foregoing amendments to the specification and claims under Article 41 of the Patent Cooperation Treaty place the application into a form for prosecution before the U.S. Patent and Trademark Office under 35 U.S.C. §371.

5 Accordingly, entry of these amendments before examination on the merits is hereby requested.

Respectfully submitted,

  
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15 ATTORNEY FOR APPLICANT

VERSION MARKED TO SHOW CHANGES

The Specification has been amended as follows:

S P E C I F I C A T I O N

TITLE

5      **ELECTRONIC CONTROL DEVICE WITH A PARALLEL DATABUS  
AND A METHOD FOR THE OPERATION OF THE CONTROL DEVICE**

BACKGROUND OF THE INVENTION

Field of the Invention

10     The present invention is directed to a control device with a parallel databus and to a method for the operation of the control device.

The invention is particularly directed to an electronic control device that must process a large data stream such as, for example, a control device for editing print data for a high-performance printer.

Description of the Related Art

15     A control device called an "SRA controller" (SRA: Scalable Raster Architecture) is described in the publication "*Das Druckbuch -- Technik und Technologie der Hochleistungsdrucker von Océ Printing Systems GmbH -- Drucktechnologien*", Edition 3c, May 1998, ISBN 3-00-001019-X.

20     The structure of this known control device is schematically shown in Figure 1. Such a control device 1 comprises an I/O module 2, one or more raster modules 3 and a serializer module 4. The individual modules 2 through 4 are

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connected to one another via a parallel databus 5. The raster modules 3 and the serializer module 4 are connected to one another via a further pixel bus 6. A high-performance printer 7 is connected to the serializer module 4.

The I/O module receives the print information from a computer device that  
5 can be a large computer system or a computer network as well. The print  
information is forwarded from the I/O module 2 to the raster modules 3 and the  
serializer module 4, whereby the raster modules 3 receive the print image  
information and convert it into a print image data stream that can be processed by  
the high-performance printer 7. These print image data streams are transmitted  
10 from the raster modules 3 via the pixel bus 6 to the serializer module 4, which  
forwards the data streams queued in a specific sequence and to the high-  
performance printer 7.

For example, the databus is a Multibus II (Multibus is a registered  
trademark of Intel Corp.). The Multibus II is a synchronized bus that is defined  
15 in IEEE Standard for a High-Performance Synchronous 32-Bit Bus: MULTIBUS  
II, The Institute of Electrical and Electronics Engineers, Inc., 345 East 47<sup>th</sup> Street,  
NY 10017, USA, 1988. Below, the "MULTIBUS II" is simply referred to as  
"multibus".

The modules 2 through 4 of the control device 1 are respectively provided  
20 with a processor. An inter-processor communication ensues with a message

transfer given systems based on the multibus, whereby messages with data packets having a predetermined length are communicated for the transfer of data.

There are two kinds of these messages given the multibus, namely what are referred to as unsolicited messages and solicited messages. The unsolicited 5 messages can be viewed as "intelligent interrupts", whereby up to 255 interrupt sources (the number of valid addresses) can send an unsolicited message. 28 bytes of status information can be transmitted with an unsolicited message.

The properties of an unsolicited message are that their arrival cannot be predicted by the receiver, whereby the transmission modalities (transmission rate, 10 data quantity, ...) are first negotiated with unsolicited messages (buffer request message, buffer grant message and buffer reject message).

A data transfer from the I/O module 2 to the raster modules 3 via the databus 5 is shown in a flowchart in Figure 2. The actions that occur at the I/O module are thereby shown at the left side, and the actions that are executed at the 15 raster module 3 are shown at the right side.

In step S1, the I/O module 2 sends a message to the raster module 3 that data are present. This message is generated by the processor of the I/O module. In response thereto, the raster module sends a corresponding message in step S2 if it needs data. This message is triggered by the processor of the raster module 2 [ 20 {sie}]. When the I/O module 2 has received this message, the processor programs

a DMA controller of the I/O module to send the requested data to the raster module and sends a buffer request message to the raster module (step S3). When the raster module can accept these data, its processor programs a DMA controller for the reception of the data and sends a buffer grant message to the I/O module (step S4).

The "negotiations" are ended with the reception of the buffer grant message by the I/O module, and the I/O module sends a data message containing a data packet to the raster module (step S5). Such a data message is transmitted until all data have been communicated to the raster module, whereby this is checked in a step S6.

When all data have been sent to the raster module, then the data transfer is ended (S7).

The steps S2 through S6 form a solicited message (broken-line frame), whereby the negotiation (S2 through S4) with which the data are requested is implemented with unsolicited messages. The individual messages of the steps S2 through S4 are respectively generated by the processors of the modules 2, 3.

The above-described interprocessor communication with a message transfer is described under the heading "Message Passing" in the publication by F. Mayer et al., "Message Passing-Protokolle in einem verteilten heterogenen Multibus-II-Mehrrechnersystem" Automatisierungstechnische Praxis -- ATP DE,

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Oldenburg Verlag, Munich, Volume 37, No. 12, pages 42-44, 46-50,  
XP000542307, ISSN: 0178-2320.

Published PCT Patent Application WO-A-91/06058 discloses a memory  
and data bank system for storing documents in the form of image data that  
5 comprises a memory processor unit connected to a databus that works according  
to the Multibus II protocol and, accordingly, implements the above-described  
method steps S1 through S7 in the data transfer. This memory processor unit is  
provided with an ADMA controller that, following the negotiation phase (steps S2  
through S4), automatically implements the transmission of the messages (steps S5  
10 and S6).

What are referred to as DMA controllers are known for controlling the  
read-in and output of memory signals. Their typical structure and functioning are  
described, for example, in the publication by Tietze, Schenk, "Halbleiter-  
Schaltungstechnik", Springer-Verlag (1985), pages 672-675. Typical applications  
15 and functions of DMA controllers are cited in the publication by Messmer, "PC-  
hardware", Addison-Wesley, 3rd Edition (1995), pages 515-516.

German Patent Document DE-T2-38 52 378 discloses a mechanism and a  
method for opposite flow control in a bus system, whereby the bus system is  
controlled with a bus administrator. In this known bus system, specific bus  
20 messages are employed in order to inform a process executing on a bus unit about

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a result or about an unanticipated input of another bus unit. The bus unit that receives the message knows immediately to where the message must be forwarded, instead of having to derive where the message is to be forwarded from the sender. The uninterrupted process need not return to the sender of the message in order to determine what is to be done. Since this message contains a report about what is to be done, little time is wasted determining the reason for sending the message.

A plurality of bus units can thus quickly addressed with this bus system and their processing status can be immediately modified.

## SUMMARY OF THE INVENTION

The present invention provides [is based on the object of creating of developing [sic]] a control device that comprises a parallel databus and a plurality of assemblies respectively provided with a processor that can communicate over the databus such that a large data stream can be more quickly and efficiently processed. The [Another object of the] invention also provides [is comprised in creating] a method for operating such a control device with which a large data stream can be simply and efficiently governed in the control device.

In particular, the invention provides an electronic control device with a parallel databus and a plurality of assemblies connected to the databus that respectively include a processor, a memory device and a DMA controller and that

are connected to the databus with a bus controller, data is transmitted between a transmitter assembly and a receiver assembly with messages, the bus controller of the transmitter assembly is fashioned such that, in response to a request message of the receiver assembly, it programs the DMA controller to read out data stored in the memory device of the transmitter assembly and to send them to the receiver assembly, without making use of the processor of the transmitter assembly.

In a preferred embodiment, the DMA controller is integrated into the bus controller of the transmitter assembly. The databus of one example is a data bus compatible with the MULTIBUS II. The receiver assembly may be a fail-safe counter for monitoring the message transfer that is restarted upon reception of a data message.

The present invention also provides a method for operating an electronic device, where the electronic control device includes a parallel databus and a plurality of assemblies connected to the databus that are respectively provided with a processor and a memory device and are connected to the databus with a bus controller, whereby data are transmitted between a transmitter assembly and a receiver assembly with messages, and the receiver assembly initiates a data transfer by sending a request message to the transmitter module, and the bus controller of the transmitter assembly, without making use of the processor of the transmitter assembly, transmits data stored in the memory device of the

transmitter assembly to the receiver assembly in response to the request message.

Preferably, a control device as set forth in the foregoing is employed. In one embodiment, following the reception of a request message, the bus controller of the transmitter assembly sends a plurality of data messages respectively

5 containing a data packet to the receiver assembly. For example, information for programming a DMA controller arranged at the transmitter assembly for reading and sending the data stored in the memory device of the transmitter assembly are transmitted with the request message. A DMA controller arranged on the transmitter assembly may be programmed by the bus controller on the basis of

10 data communicated with the request message, being programmed to read and transmit the data stored in the memory device of the transmitter assembly. The DMA controller arranged on the receiver assembly is programmed for the reception of the data with the transmission of the request message. In one embodiment, the data are transmitted with a plurality of messages that respectively contain a data

15 packet. The transmitter assembly may include a buffer wherein an entry is provided for each assembly present in the control device, so that the parameters characterizing the data transfer are written into the respective entry and stored during a data transfer and are erased after the conclusion of the data transfer.

Specifically, upon reception of a request message, the bus controller of the

20 transmitter assembly checks whether the entry of the buffer allocated to the

assembly sending the request message is already written with data characterizing a data transfer in order to prevent two data transfers from being simultaneously initiated with the same receiver assembly.

The invention also provides a control device for editing print data for a  
5 high-performance printer, with the features set forth above whereby the transmitter assembly forms an I/O module and a plurality of receiver modules that respectively form a raster module are provided.

[The object is achieved by a device having the features of claim 1 and by a method having the features of claim 6. Advantageous developments of the  
10 invention are recited in the subclaims.]

The inventive electronic control device is provided with a parallel databus and a plurality of assemblies connected to the databus that respectively comprise a processor and a memory device and are connected to the databus bus with a bus controller, whereby data are transmitted between a transmitter assembly and a receiver assembly with messages. The invention is characterized in that the bus controller of the transmitter assembly is fashioned such that, without making use of the processor of the transmitter assembly, it reads data stored in the memory device of the transmitter assembly in response to a request message of the receiver assembly and transmits them to the receiver assembly. The receiver assembly thus triggers an automatic transmission of the data at the transmitter assembly on  
15  
20

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the basis of its request message. This leads to a considerable unburdening of the transmitter assembly since the data can be directly read with a DMA controller significantly faster and more efficiently, and the processor is not occupied long by such a data transmission. Moreover, the initially described "negotiation", which 5 comprises three message transmissions given the traditional multibus (see Figure 2), is reduced to the transmission of a single request message, as a result whereof a further simplification and acceleration of the transmission procedure is achieved.

The method for the operation of such an electronic control device [recited  
in claim 6] is characterized in that the receiver assembly initiates a data transfer  
10 by sending the request message to the transmitter assembly, and the bus controller  
of the transmitter assembly, without making use of the processor of the transmitter  
assembly, reads data stored in the memory device of the transmitter assembly in  
response to the request message and transmits them to the receiver assembly. As  
15 a result thereof, a large data stream can be quickly and efficiently transmitted  
from the transmitter assembly to the receiver assembly, so that the control device  
can govern a large data stream.

In a preferred embodiment of the invention, the data needed for  
programming a DMA controller arranged on the transmitter assembly are  
communicated from the receiver assembly to the transmitter assembly by means  
20 of the request message. With the request message, thus, the receiver assembly

controls the data transmission from the transmitter assembly.

With the inventive method, the individual receiver assemblies can independently and simultaneously fetch the data they want from the transmitter assembly. As a result of the automatic processing of the request messages in the transmitter assembly, this can make the data available very fast. The simplification of the transmission protocol effects a further speed-up of the transmission procedure.

#### BRIEF DESCRIPTION OF THE DRAWINGS

The invention is explained in greater detail below on the basis of an exemplary embodiment shown in the drawings. [Shown schematically are:]

Figure 1 shows the fundamental structure of a control device for editing print data for a high-performance printer in a block circuit diagram;

Figure 2 is a flowchart of a data transfer according to a transmission method known from the multibus;

Figure 3 is a block diagram showing two assemblies connected via a databus;

Figure 4 shows the inventive data transfer in a flowchart;

Figure 5 shows the structure of a request message in a block circuit diagram;

Figure 6 shows the structure of a data message in a block circuit diagram;

DE 30 200 700 800 900 000

and

Figure 7 shows the structure of an entry in a buffer provided at the transmitter assembly in a block circuit diagram.

#### DETAILED DESCRIPTION OF THE PREFERRED EMBODIMENTS

5       The present invention is explained on the basis of an exemplary embodiment of an electronic control device 1 for controlling a high-performance printer that has the same structure as the known control device shown in Figure 1 and that is provided with an I/O module 2, one or more raster modules 3 and a serializer module 4. The individual modules 2 through 4 are connected to one another via a parallel databus 5. The raster modules 3 and the serializer module 4 are connected to one another via a further pixel bus 6. The high-performance printer 7 is connected to the serializer module 4.

10      The databus 5 is a development of the multibus and is essentially compatible therewith.

15      The modules 2 through 4 respectively represent an assembly 8 connected to the databus. Two such assemblies [assembly sie] 8, namely the I/O module 2 and the raster module 3 [4 sie], are schematically shown in Figure 3.

20      The assemblies 8 respectively comprise a bus controller 9 that are each [sie] provided with an internal DMA controller 10 integrated into the bus controller 9. The assemblies respectively have a processor 11 and memory

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devices 12 that are connected to one another and to the bus controller 9 with an internal computer bus 13. The assemblies 8 comprise further elements such as, for example, components and lines for further interfaces and the like that, however, are not shown in Figure 3 for reasons of simplification.

5       The inventive, automatic requested message transfer is explained below on the basis of the flowchart shown in Figure 4. The actions that occur at the I/O module 2 are thereby again shown at the left aside, and the actions that are implemented at the raster module 3 are shown at the right side.

10      During the step S1, the I/O module 2 sends a message to a raster module 3 that data are present. This message is generated by the processor of the I/O module and corresponds to the step Si according to the known method shown in Figure 2.

15      In response thereto, the raster module 3 checks in a step S8 whether it needs the data offered by the I/O module 2 and whether there is enough memory space for the acceptance of the data. This check is carried out by the processor 11 of the raster module 3.

20      When these data are not present, the processor 11 -- in a step S9 -- programs the DMA controller 10 in the bus controller 9 for the reception of a data packet and write a data request message into the bus controller 9. The data request message contains the address of the data in the memory of the I/o module

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2, the plurality of data bytes that are to be transmitted, and what is referred to as a duty cycle for the transmission of the requested messages. The duty cycle defines the spacing in which the requested messages are sent via the data bus 5. Over and above this, further data can also be contained in the data request message that 5 define the respective data transfer in greater detail. The structure of this data request message is shown in Figure 5. The data request message represents an unsolicited message. The message type has the value 02H.

During the step S10, the bus controller 9 of the raster module 3 sends this data request message to the I/O module 2 via the databus 5.

10 Based on the criterion of the data (address of the data in the memory of the I/O module, plurality of data bytes, duty cycle, etc.) contained in the data request message, the bus controller 9 of the I/O module 2 programs its DMA controller 10 with the address and the number [plurality] of bytes of a data message to be transmitted (step S11).

15 The structure of such a data message is shown in Figure 6. A data message comprises a source address and a destination address, whereby the occupancy of the data request message is valid therefor, so that the source address is the address of the receiver assembly and the destination address is the address of the transmitter assembly. Two types of data message are provided, namely the 20 type 3CH and the type 3DH, whose significance shall be explained later. A data

packet with 32 bytes (byte 0 through byte 31) can be transmitted with the data message shown in Figure 6.

For sending the data message shown in Figure 6, the bus controller starts the DMA controller 10 in step S12 and packs the data communicated from the 5 DMA controller 10 to the bus controller 9 into a data packet. The data packet [packets [sie]] is transmitted from the I/O module 2 to the raster module 3 with a data message via the databus 5.

A check is carried out in step S13 as to whether all data have already been transmitted. When further data have to be transmitted, then the program runs 10 returns to the step S12, as a result whereof the next data message is transmitted. This procedure is repeated until all data have been transmitted in packets from the I/O module to the raster module. All of the data messages except the last data message that are thereby employed are of the type 3CH. The last data message is of the type 3DH. The [the] data transfer has been ended with the transmission of 15 all data packets (step S14). Due to the reception of the data message of the type 3DH, an interrupt is triggered at the raster module 3 that indicates to the processor of the raster module 3 that the requested data transfer has been ended. A message to the processor of the I/O module 2 only ensues when an error has occurred in the transmission of the data.

20 The steps S8 through S14 forms the automatic requested message transfer

(broken-line frame). This automatically requested message transfer comprises only one unsolicited message, namely the data request message of the step S10, and the solicited data messages of the step S14. Compared to the solicited messages of the known multibus, the number of unsolicited messages is reduced  
5 from 3 th 1. A significant unburdening at the databus 5 is thereby achieved.

A defined data quantity of, for example, 4 KB is transmitted with such an automatic requested message transfer.

A buffer is provided in the bus controller 9 of the I/O module 2 wherein the parameters of the automatically requested message transfers can be deposited.  
10 One entry is provided in this buffer for each assembly 8 that can function as receiver assembly 3. In the present exemplary embodiment, the buffer comprises 21 entries. The parameters contained in the entries are (Figure 7):  
21

1. source and destination address for the automatic requested message transfer,
- 15 2. duty cycle for the data packets,
3. DMA address of the data in the memory device, and
4. plurality of data bytes.

Upon reception of a request message, the bus controller 9 of the I/O module can check whether the entry of the buffer allocated to the raster module 3  
20 sending the request message is already described with data characterizing a data

transfer. When the data of another automatically requested message transfer are already contained in the entry, an error message can be output and the request message can be rejected in order to prevent two message transfers from being simultaneously initiated with the same raster module.

5       The bus controller 9 sees to it that the request messages are processed in the sequence of their arrival. This assures that each raster module has a turn.

Given an occupied entry in the buffer or given an occupied input buffer wherein the arriving messages are intermediately stored, the request message is rejected with the error message NACK. The request message is subsequently 10 repeated until it can either be processed or the number of repetitions defined in the protocol has been reached. When the data messages cannot be received by the raster module 3, the error NACK is also output and they are repeated until they can be accepted or until the defined plurality of repetitions has been reached.

When a raster module has initiated an automatic requested message 15 transfer and sends further data request messages during its own transfer, then these messages are not transmitted. Instead, a transmit error is reported. Upon readout of the rejected unsolicited message from an error FIFO known by the multibus, a "no resource" bit is set.

When a DMA error occurs during the reception of the data at the raster 20 module 3, then a corresponding status bit is set in the DMA controller 10 of the

bus controller 9 and the DMA controller ends the transfer on its own. When no immediate actions are triggered at the processor as a result thereof, then the following executive sequence derives:

An internal buffer of the raster module 3 for the reception of the data  
5 messages fills up. The raster module therefore rejects further data messages. The bus controller of the I/O module repeats a rejected data message for a maximum of 127 times and then ends the data transfer on its own. The bus controller 9 of the I/O module subsequently reports the situation to its processor.

In addition, an internal fail-safe counter runs down at the raster module,  
10 this being always set to its start value by the reception of a data message. The rundown of the counter is communicated to the processor of the raster module, which subsequently implements an error recovery known from the multibus.

In a preferred embodiment of the invention for accelerating the above executive sequence at the side of the raster module (the fail-safe counter runs  
15 down in approximately 2 seconds), the processor of the raster module can already react to the DMA error in that it stops the DMA reception channel of the transfer and communicates the end of the transfer via an unsolicited message to the I/O module. The stopping ensues at the I/O module by an erase instruction output by the bus controller to erase the corresponding DMA reception channel.

20 When a DMA error occurs at the I/O module, the DMA channel is stopped

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by the internal executive sequencer -- as in the case of an error at the raster module -- and the corresponding status bits are set. Additionally, an unsolicited message is sent to the raster module, so that this stops the reception of the data message. Due to this message, the processor of the raster module forwards a stop instruction to the DMA controller and an erase instruction to the reception channel of the automatically requested message transfer. When the processor of the I/O module does not react to the DMA error, then the aforementioned fail-safe counter on the raster module runs down. Subsequently, the processor of the raster module must send an unsolicited message to the I/O module, so that the I/O module also ends the transfer.

The aforementioned fail-safe counter of the raster module is provided for the reception of the data messages and is restarted every time after the reception of a data message of the type 3CH. It runs down when no further data message is received within the time that has been set. In this case, the processor of the raster module stops the DMA channel in the bus controller and the reception channel of the automatically requested message transfer is erased. Additionally, an unsolicited message is sent to the I/O module so that the I/O module can stop the automatic requested message transfer. A stop instruction for the DMA channel of the I/o module is thereby not necessary since this is undertaken by the internal executive sequences of the bus controller.

A running, automatic requested message transfer at the raster module can be aborted with an erase instruction at the corresponding reception channel. The instruction takes immediate effect. All data messages arriving thereafter are rejected by the bus controller with an error message "transfer not understood" that is known from the multibus. The termination of the reception channel of the DMA controller must likewise be implemented by the processor.

A running, automatic requested message transfer is aborted or, respectively, arrested at the I/o module as a result of the following actions:

a) An error has occurred at the databus. All errors come into consideration:

- 10           • The repetition rate for a data message has reached the maximum value.  
              • a bus error, bus timeout or an agent error occurred in the transmission of the data message.

b) An error occurred in the DMA transmission. The following errors come 15 into consideration:

- parity error
- page miss error
- fatal error given a transfer via the internal computer bus (PCI bus).

c) The processor aborts the running, automatic requested message transfer 20 with a command.

In cases a) [aθ] and b), the automatic, requested message transfer is aborted by the internal controller of the bus controller due to the error. The internal controller reports the cause of the error by setting an ASOMERR bit in a message status register. When a corresponding interrupt is enabled in a message control register, then an interrupt is additionally generated. The processor of the I/O module can determine the cause of the error by reading out an ASOM status register allocated to the automatic, requested message transfer. Before an automatic, requested message transfer can be resumed, the processor of the I/O module must output a corresponding command (ASOMGO).

The processor cannot abort an running, automatic requested message transfer at any time (see c). Dependent on the command employed, the automatic requested message transfer is still completely implemented or is immediately interrupted. It must be taken into consideration in the latter case that the raster module is waiting for the further arrival of data messages. A corresponding message is therefore sent from the I/O module to the raster module given an interruption of an automatically requested message transfer.

For logging the automatic requested message transfer, the following options can be established at the I/O module:

1. Each automatic requested message transfer is forwarded to the processor of the I/O module. Which assembly requested an automatic requested

message transfer can thus be kept track of on the I/O module.

2. A register is provided in the bus controller that contains the message ID of the assembly requesting the automatic requested message transfer. This register is set to the message ID at the beginning of the transfer and is in turn reset at the end. The register can be read out at any time by the processor.

The invention has been set forth above on the basis of a control device for editing print data for a high-performance printer. The inventive control device is equally suited for any application wherein a large data stream must be processed.

- 10 The I/O module, accordingly, can be considered in general as a transmitter assembly and the raster module can be considered as a receiver module, whereby the data are transmitted from the transmitter module to the receiver module.

In the above-described exemplary embodiment, a databus is employed that is essentially compatible with the multibus. The invention, however, is not limited to this type of databus but can be designed for any parallel databus that is suitable for a multi-processor architecture.

A DMA controller 10 integrated into the bus controller 9 is provided in the assemblies recited in the exemplary embodiment.

20 In the framework of the invention, of course, the DMA controller 10 can also be arranged outside the bus controller 9 on the assembly.

The above-described data messages respectively transmit a data packet of 32 bytes. The size of these data packets can be varied as needed and, for example, comprise 64 or 128 bytes. The data quantity transferred with an automatic requested message transfer can be fixed to any desired size of, for example, 4 KB,  
5 8 KB, 16 KB or the like.

The invention can be summarized in brief in the following way:  
It is directed to an electronic control device with a parallel databus and a plurality  
of assemblies connected to the databus. The assemblies respectively comprise a  
processor and a memory device and are connected to the databus with a bus  
10 controller. The data are transmitted between a transmitter assembly and a receiver  
assembly with messages. The data bus essentially corresponds to the  
MULTIBUS II.

The invention is characterized in that the bus controller of the transmitter  
assembly is fashioned such that, without making use of the processor of the  
15 transmitter assembly, it reads data stored in the memory device of the transmitter  
assembly in response to a request message of the receiver assembly and sends  
them to the receiver assembly.

As a result thereof, first, the processor of the transmitter assembly (I/O  
module) is relieved and, second, the communication between the transmitter  
20 assembly and the receiver assembly (raster module) can be significantly lowered

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and reduced to a single request message in the negotiation or, respectively, determination of the data transfer. The electronic control device is preferably fashioned for a control device for driving a high-performance printer.

Although other modifications and changes may be suggested by those  
5 skilled in the art, it is the intention of the inventors to embody within the patent  
warranted hereon all changes and modifications as reasonably and properly come  
within the scope of their contribution to the art.

[List of Reference Characters

- 1. electronic control devicee
- 2. I/O module
- 3. raster module
- 5 4. serializer module
- 5. databus
- 6. pixel bus
- 7. high performance printer
- 8. assembly
- 10 9. bus controller
- 10. DMA controller
- 11. processor
- 12. memory device
- 13. internal computer bus ]

The claims have been amended as follows:

**We claim: [Claims]**

- 1.(Amended) An electronic [Electronie] control device, comprising: [with]  
a parallel databus; [(5) and]  
5 a plurality of assemblies [(8)] connected to said parallel [the] databus, said  
plurality of assemblies each including: [(5) that respectively comprise]  
a processor [(11)],  
a memory device; [(12) and]  
a DMA controller; [(10) and that are connected to the databus (5) with]  
10 a bus controller connecting said plurality of assemblies to said parallel databus  
such that [(9), whereby] data are transmitted between a transmitter  
assembly of said plurality of assemblies and a receiver assembly of said  
plurality of assemblies with messages, [whereby] the bus controller [(9)]  
of the transmitter assembly being [is] fashioned such that the transmitter  
15 assembly [, in response to a request message of the receiver assembly, it]  
programs the DMA controller to read out data stored in the memory device  
[(12)] of the transmitter assembly and to send them to the receiver  
assembly in response to a request message of the receiver assembly [,]  
without making use of the processor [(11)] of the transmitter assembly.

2.(Amended) An electronic [Electronie] control device according to claim 1, wherein [echaraterized in that] the DMA controller [(10)] is integrated into the bus controller [(9)] of the transmitter assembly.

3.(Amended) An electronic [Electronie] control device according to claim 5 1, wherein [or 2, whereby] the databus [(5)] is a data bus compatible with [the] MULTIBUS II.

4. (Amended) An electronic [Electronie] control device according to claim [one of the claims] 1, wherein [through 3, characterized in that] the receiver assembly includes [eomprises] a fail-safe counter for monitoring [the] message transfer that is restarted upon reception of a data message.

10 5.(Amended) A method [Method] for operating [the operation of] an electronic device, [whereby] the electronic control device including [eomprises] a parallel databus [(5)] and a plurality of assemblies [(2)] connected to the databus that are respectively provided with a processor [(11)] and a memory device [(12)] and are connected to the databus [(5)] with a bus controller [(9)], comprising the steps of: [whereby] transmitting data [are transmitted] between a transmitter assembly and a receiver

5

assembly with messages; [~~and the receiver assembly initiates~~]  
initiating a data transfer by sending a request message from the receiver assembly  
to the transmitter module; and [~~and the bus controller (9) of the~~  
~~transmitter assembly, without making use of the processor of the~~  
~~transmitter assembly, transmits~~]  
transmitting data stored in the memory device [(12)] of the transmitter assembly  
to the receiver assembly in response to the request message without  
making use of the processor of the transmitter assembly from the bus  
controller of the transmitter assembly.

10

6. (Amended) A method [Method] according to claim 5, further  
comprising the step of: [whereby]  
utilizing a control device having

15

a parallel databus;  
a plurality of assemblies connected to said parallel databus, said plurality  
of assemblies each including:  
a processor,  
a memory device;  
a DMA controller;  
a bus controller connecting said plurality of assemblies to said parallel

0 9 8 0 7 6 5 2 1 0 9 8 7 6 5 4 3 2 1 0

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databus such that data are transmitted between a transmitter assembly of said plurality of assemblies and a receiver assembly of said plurality of assemblies with messages, the bus controller of the transmitter assembly being fashioned such that the transmitter assembly programs the DMA controller to read out data stored in the memory device of the transmitter assembly and to send them to the receiver assembly in response to a request message of the receiver assembly without making use of the processor of the transmitter assembly [according to one of the claims 1 through 4 is employed].

10

7. (Amended) A method [Method] according to claim 5, further comprising the step of: [or 6, whereby, following the reception of a request message, the bus controller (9) of the transmitter assembly sends] sending a plurality of data messages respectively containing a data packet to the receiver assembly from the bus controller of the transmitter assembly following reception of a request message.

15

8. (Amended) A method [Method] according to claim [one of the claims] 5, further comprising the step of: [through 7, whereby]

transmitting information for programming a DMA controller [(10)] arranged at the transmitter assembly for reading and sending the data stored in the memory device [(12)] of the transmitter assembly [~~are transmitted~~] with the request message .

5           9. (Amended) A method [Method] according to claim [one of the claims]

5, further comprising the step of: [through 8, whereby]  
programming a DMA controller [(10)] arranged on the transmitter assembly [~~is programmed~~] by the bus controller [(9)] on a [~~the~~] basis of data communicated with the request message, being programmed to read and  
10 transmit the data stored in the memory device [(12)] of the transmitter assembly.

15           10. (Amended) A method [Method] according to claim [one of the claims] 5, further comprising the steps of: [through 9, whereby]  
programming a DMA controller [(10)] arranged on the receiver assembly [~~is programmed~~] for [~~the~~] reception of the data with the transmission of the request message.

11. (Amended) A method [Method] according to claim [one of the claims]

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5, further comprising the step of: [through 10, whereby]  
transmitting the data [are transmitted] with a plurality of messages that  
respectively contain a data packet.

12. (Amended) A method [Method] according to claim [one of the claims]  
5   5, further comprising the step of: [through 11, whereby the transmitter assembly  
comprises a buffer wherein]  
providing an entry in a buffer of the transmitter is provided for each assembly  
present in the control device, so that the parameters characterizing the data  
transfer are written into the respectively entry and stored during a data  
10   transfer and are erased after the conclusion of the data transfer.

13. (Amended) A method [Method] according to claim 12, [whereby,]  
upon reception of a request message, checking by the bus controller of the  
transmitter assembly [checks] whether the entry of the buffer allocated to  
the assembly sending the request message is already written with data  
15   characterizing a data transfer in order to prevent two data transfers from  
being simultaneously initiated with the same receiver assembly.

14. (Amended) A control [Control] device for editing print data for a high-

performance printer, comprising:

a parallel databus;

a plurality of assemblies connected to said parallel databus, said plurality of assemblies each including:

5           a processor.

a memory device;

a DMA controller;

a bus controller connecting said plurality of assemblies to said parallel databus such that data are transmitted between a transmitter assembly of said plurality of assemblies and a receiver assembly of said plurality of assemblies with messages, the bus controller of the transmitter assembly being fashioned such that the transmitter assembly programs the DMA controller to read out data stored in the memory device of the transmitter assembly and to send them to the receiver assembly in response to a request message of the receiver assembly without making use of the processor of the transmitter assembly [the features of one of the claims 1 through 4, whereby] the transmitter assembly forming [forms] an I/O module [(2)] and a plurality of receiver modules that respectively form a raster module [(3) are provided].

10           15  
               request message of the receiver assembly without making use of the processor of the transmitter assembly [the features of one of the claims 1 through 4, whereby] the transmitter assembly forming [forms] an I/O module [(2)] and a plurality of receiver modules that respectively form a raster module [(3) are provided].

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The Abstract has been amended as follows:

ABSTRACT OF THE DISCLOSURE

An electronic control device with a parallel databus and a plurality of assemblies connected to the databus. The assemblies each include a processor and a memory device and are connected to the databus with a bus controller. The data are transmitted between a transmitter assembly and a receiver assembly with messages. The data bus essentially corresponds to the MULTIBUS II. The bus controller of the transmitter assembly is fashioned such that, without making use of the processor of the transmitter assembly, it reads data stored in the memory device of the transmitter assembly in response to a request message of the receiver assembly and sends them to the receiver assembly.

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**ELECTRONIC CONTROL DEVICE WITH A PARALLEL DATABUS AND A  
METHOD FOR THE OPERATION OF THE CONTROL DEVICE**

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The invention is directed to a control device with a parallel databus and to a method for the operation of the control device.

5 The invention is particularly directed to an electronic control device that must process a large data stream such as, for example, a control device for editing print data for a high-performance printer.

A control device called an "SRA controller" (SRA: Scalable raster architecture) is described in "*Das Druckbuch -- Technik und Technologie der*  
10 *Hochleistungsdrucker von Océ Printing Systems GmbH -- Drucktechnologien*",  
Edition 3c, May 1998, ISBN 3-00-001019-X.

The structure of this known control device is schematically shown in Figure 1. Such a control device 1 comprises an I/O module 2, one or more raster modules 3 and a serializer module 4. The individual modules 2 through 4 are connected to one another via a parallel databus 5. The raster modules 3 and the serializer module 4 are connected to one another via a further pixel bus 6. A high-performance printer 7 is connected to the serializer module 4.

15 The I/O module receives the print information from a computer device that can be a large computer system or a computer network as well. The print information is forwarded from the I/O module 2 to the raster modules 3 and the serializer module 4, whereby the raster modules 3 receive the print image information and convert it into a print image data stream that can be processed by the high-performance printer 7. These print image data streams are transmitted from the raster modules 3 via the pixel bus 6 to the serializer module 4, which forwards the data streams queued in a specific sequence and to the high-performance printer 7.

20 For example, the databus is a Multibus II (Multibus is a registered trademark of Intel Corp.). The Multibus II is a synchronized bus that is defined in IEEE Standard for a High-Performance Synchronous 32-Bit Bus: MULTIBUS II, The Institute of Electrical and Electronics Engineers, Inc., 345 East 47<sup>th</sup> Street, NY 10017,  
30 USA, 1988. Below, the "MULTIBUS II" is simply referred to as "multibus".

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The modules 2 through 4 of the control device 1 are respectively provided with a processor. An inter-processor communication ensues with a message transfer given systems based on the multibus, whereby messages with data packets having a predetermined length are communicated for the transfer of data.

5 There are two kinds of these messages given the multibus, namely what are referred to as unsolicited messages and solicited messages. The unsolicited messages can be viewed as "intelligent interrupts", whereby up to 255 interrupt sources (the number of valid addresses) can send an unsolicited message. 28 bytes of status information can be transmitted with an unsolicited message.

10 The properties of an unsolicited message are that their arrival cannot be predicted by the receiver, whereby the transmission modalities (transmission rate, data quantity, ...) are first negotiated with unsolicited messages (buffer request message, buffer grant message and buffer reject message).

15 A data transfer from the I/O module 2 to the raster modules 3 via the databus 5 is shown in a flowchart in Figure 2. The actions that occur at the I/O module are thereby shown at the left side, and the actions that are executed at the raster module 3 are shown at the right side.

20 In step S1, the I/O module 2 sends a message to the raster module 3 that data are present. This message is generated by the processor of the I/O module. In response thereto, the raster module sends a corresponding message in step S2 if it needs data. This message is triggered by the processor of the raster module 2 [sic]. When the I/O module 2 has received this message, the processor programs a DMA controller of the I/O module to send the requested data to the raster module and sends a buffer request message to the raster module (step S3). When the raster module can accept these data, its processor programs a DMA controller for the reception of the data and sends a buffer grant message to the I/O module (step S4).

25 The "negotiations" are ended with the reception of the buffer grant message by the I/O module, and the I/O module sends a data message containing a data packet to the raster module (step S5). Such a data message is transmitted until all data have been communicated to the raster module, whereby this is checked in a step S6.

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When all data have been sent to the raster module, then the data transfer is ended (S7).

The steps S2 through S6 form a solicited message (broken-line frame), whereby the negotiation (S2 through S4) with which the data are requested is

5 implemented with unsolicited messages. The individual messages of the steps S2 through S4 are respectively generated by the processors of the modules 2, 3.

The above-described interprocessor communication with a message transfer is described under the heading "Message Passing" in F. Mayer et al., "Message Passing-Protokolle in einem verteilten heterogenen Multibus-II-

10 Mehrrechnersystem" Automatisierungstechnische Praxis -- ATP DE, Oldenburg Verlag, Munich, Volume 37, No. 12, pages 42-44, 46-50, XP000542307, ISSN: 0178-2320.

WO-A-91/06058 discloses a memory and data bank system for storing documents in the form of image data that comprises a memory processor unit

15 connected to a databus that works according to the Multibus II protocol and, accordingly, implements the above-described method steps S1 through S7 in the data transfer. This memory processor unit is provided with an ADMA controller that, following the negotiation phase (steps S2 through S4), automatically implements the transmission of the messages (steps S5 and S6).

20 What are referred to as DMA controllers are known for controlling the read-in and output of memory signals. Their typical structure and functioning are described, for example, in Tietze, Schenk, "Halbleiter-Schaltungstechnik", Springer-Verlag (1985), pages 672-675. Typical applications and functions of DMA

25 controllers are cited in Messmer, "PC-hardware", Addison-Wesley, 3<sup>rd</sup> Edition (1995), pages 515-516.

DE-T2-38 52 378 discloses a mechanism and a method for opposite flow control in a bus system, whereby the bus system is controlled with a bus administrator. In this known bus system, specific bus messages are employed in order to inform a process executing on a bus unit about a result or about an unanticipated

30 input of another bus unit. The bus unit that receives the message knows immediately to where the message must be forwarded, instead of having to derive where the

message is to be forwarded from the sender. The uninterrupted process need not return to the sender of the message in order to determine what is to be done. Since this message contains a report about what is to be done, little time is wasted  
5 determining the reason for sending the message.

A plurality of bus units can thus quickly addressed with this bus system and their processing status can be immediately modified.

The invention is based on the object of creating of developing [sic] a control device that comprises a parallel databus and a plurality of assemblies  
10 respectively provided with a processor that can communicate over the databus such that a large data stream can be more quickly and efficiently processed. Another object of the invention is comprised in creating a method for operating such a control device

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with which a large data stream can be simply and efficiently governed in the control device.

The object is achieved by a device having the features of claim 1 and by a method having the features of claim 6. Advantageous developments of the invention  
5 are recited in the subclaims.

The inventive electronic control device is provided with a parallel databus and a plurality of assemblies connected to the databus that respectively comprise a processor and a memory device and are connected to the databus bus with a bus controller, whereby data are transmitted between a transmitter assembly and a receiver  
10 assembly with messages. The invention is characterized in that the bus controller of the transmitter assembly is fashioned such that, without making use of the processor of the transmitter assembly, it reads data stored in the memory device of the transmitter assembly in response to a request message of the receiver assembly and transmits them to the receiver assembly. The receiver assembly thus triggers an  
15 automatic transmission of the data at the transmitter assembly on the basis of its request message. This leads to a considerable unburdening of the transmitter assembly since the data can be directly read with a DMA controller significantly faster and more efficiently, and the processor is not occupied long by such a data transmission. Moreover, the initially described "negotiation", which comprises three  
20 message transmissions given the traditional multibus (see Figure 2), is reduced to the transmission of a single request message, as a result whereof a further simplification and acceleration of the transmission procedure is achieved.

The method for the operation of such an electronic control device recited in claim 6 is characterized in that the receiver assembly initiates a data transfer by  
25 sending the request message to the transmitter assembly, and the bus controller of the transmitter assembly, without making use of the processor of the transmitter assembly, reads data stored in the memory device of the transmitter assembly in response to the request message and transmits them to the receiver assembly. As a result thereof, a large data stream can be quickly and efficiently transmitted from the  
30 transmitter assembly to the receiver assembly, so that the control device can govern a large data stream.

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In a preferred embodiment of the invention, the data needed for programming a DMA controller arranged on the transmitter assembly are communicated from the receiver assembly to the transmitter assembly by means of the request message. With the request message, thus, the receiver assembly controls the data transmission from the transmitter assembly.

With the inventive method, the individual receiver assemblies can independently and simultaneously fetch the data they want from the transmitter assembly. As a result of the automatic processing of the request messages in the transmitter assembly, this can make the data available very fast. The simplification of the transmission protocol effects a further speed-up of the transmission procedure.

The invention is explained in greater detail below on the basis of an exemplary embodiment shown in the drawings. Shown schematically are:

Figure 1 the fundamental structure of a control device for editing print data for a high-performance printer in a block circuit diagram;

Figure 2 a flowchart of a data transfer according to a transmission method known from the multibus;

Figure 3 two assemblies connected via a databus;

Figure 4 the inventive data transfer in a flowchart;

Figure 5 the structure of a request message in a block circuit diagram;

Figure 6 the structure of a data message in a block circuit diagram;

Figure 7 the structure of an entry in a buffer provided at the transmitter assembly in a block circuit diagram.

The invention is explained on the basis of an exemplary embodiment of an electronic control device 1 for controlling a high-performance printer that has the same structure as the known control device shown in Figure 1 and that is provided with an I/O module 2, one or more raster modules 3 and a serializer module 4. The individual modules 2 through 4 are connected to one another via a parallel databus 5. The raster modules 3 and the serializer module 4 are connected to one another via a further pixel bus 6. The high-performance printer 7 is connected to the serializer module 4.

The databus 5 is a development of the multibus and is essentially compatible therewith.

The modules 2 through 4 respectively represent an assembly 8 connected to the databus. Two such assembly [sic] 8, namely the I/O module 2 and the raster module 4 [sic], are schematically shown in Figure 3.

The assemblies 8 respectively comprise a bus controller 9 that are [sic] provided with an internal DMA controller 10 integrated into the bus controller 9. The assemblies respectively have a processor 11 and memory devices 12 that are connected to one another and to the bus controller 9 with an internal computer bus 13.

10 The assemblies 8 comprise further elements such as, for example, components and lines for further interfaces and the like that, however, are not shown in Figure 3 for reasons of simplification.

The inventive, automatic requested message transfer is explained below on the basis of the flowchart shown in Figure 4. The actions that occur at the I/O module 2 are thereby again shown at the left aside, and the actions that are implemented at the raster module 3 are shown at the right side.

During the step S1, the I/O module 2 sends a message to a raster module 3 that data are present. This message is generated by the processor of the I/O module and corresponds to the step Si according to the known method shown in Figure 2.

20 In response thereto, the raster module 3 checks in a step S8 whether it needs the data offered by the I/O module 2 and whether there is enough memory space for the acceptance of the data. This check is carried out by the processor 11 of the raster module 3.

When these data are not present, the processor 11 -- in a step S9 -- programs the DMA controller 10 in the bus controller 9 for the reception of a data packet and write a data request message into the bus controller 9. The data request message contains the address of the data in the memory of the I/O module 2, the plurality of data bytes that are to be transmitted, and what is referred to as a duty cycle for the transmission of the requested messages. The duty cycle defines the spacing in which the requested messages are sent via the data bus 5. Over and above this, further data can also be contained in the data request message that define the respective data

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transfer in greater detail. The structure of this data request message is shown in Figure 5. The data request message represents an unsolicited message. The message type has the value 02H.

During the step S10, the bus controller 9 of the raster module 3 sends this  
5 data request message to the I/O module 2 via the databus 5.

Based on the criterion of the data (address of the data in the memory of the I/O module, plurality of data bytes, duty cycle, etc.) contained in the data request message, the bus controller 9 of the I/O module 2 programs its DMA controller 10 with the address and the plurality of bytes of a data message to be transmitted (step

10 S11).

The structure of such a data message is shown in Figure 6. A data message comprises a source address and a destination address, whereby the occupancy of the data request message is valid therefor, so that the source address is the address of the receiver assembly and the destination address is the address of the transmitter assembly. Two types of data message are provided, namely the type 3CH and the type 3DH, whose significance shall be explained later. A data packet with 32 bytes (byte 0 through byte 31) can be transmitted with the data message shown in Figure 6.

For sending the data message shown in Figure 6, the bus controller starts  
20 the DMA controller 10 in step S12 and packs the data communicated from the DMA controller 10 to the bus controller 9 into a data packet. The data packets [sic] is transmitted from the I/O module 2 to the raster module 3 with a data message via the databus 5.

A check is carried out in step S13 as to whether all data have already been  
25 transmitted. When further data have to be transmitted, then the program runs returns to the step S12, as a result whereof the next data message is transmitted. This procedure is repeated until all data have been transmitted in packets from the I/O module to the raster module. All of the data messages except the last data message that are thereby employed are of the type 3CH. The last data message is of the type  
30 3DH. the data transfer has been ended with the transmission of all data packets (step S14). Due to the reception of the data message of the type 3DH, an interrupt is

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triggered at the raster module 3 that indicates to the processor of the raster module 3 that the requested data transfer has been ended. A message to the processor of the I/O module 2 only ensues when an error has occurred in the transmission of the data.

The steps S8 through S14 forms the automatic requested message transfer  
5 (broken-line frame). This automatically requested message transfer comprises only one unsolicited message, namely the data request message of the step S10, and the solicited data messages of the step S14. Compared to the solicited messages of the known multibus, the number of unsolicited messages is reduced from 3 th 1. A significant unburdening at the databus 5 is thereby achieved.

10 A defined data quantity of, for example, 4 KB is transmitted with such an automatic requested message transfer.

A buffer is provided in the bus controller 9 of the I/O module 2 wherein the parameters of the automatically requested message transfers can be deposited. One entry is provided in this buffer for each assembly 8 that can function as receiver  
15 assembly 3. In the present exemplary embodiment, the buffer comprises 21 entries. The parameters contained in the entries are (Figure 7):

1. source and destination address for the automatic requested message transfer,
2. duty cycle for the data packets,
- 20 3. DMA address of the data in the memory device, and
4. plurality of data bytes.

Upon reception of a request message, the bus controller 9 of the I/O module can check whether the entry of the buffer allocated to the raster module 3 sending the request message is already described with data characterizing a data  
25 transfer. When the data of another automatically requested message transfer are already contained in the entry, an error message can be output and the request message can be rejected in order to prevent two message transfers from being simultaneously initiated with the same raster module.

The bus controller 9 sees to it that the request messages are processed in  
30 the sequence of their arrival. This assures that each raster module has a turn.

Given an occupied entry in the buffer or given an occupied input buffer wherein the arriving messages are intermediately stored, the request message is rejected with the error message NACK. The request message is subsequently repeated until it can either be processed or the number of repetitions defined in the 5 protocol has been reached. When the data messages cannot be received by the raster module 3, the error NACK is also output and they are repeated until they can be accepted or until the defined plurality of repetitions has been reached.

When a raster module has initiated an automatic requested message transfer and sends further data request messages during its own transfer, then these 10 messages are not transmitted. Instead, a transmit error is reported. Upon readout of the rejected unsolicited message from an error FIFO known by the multibus, a "no resource" bit is set.

When a DMA error occurs during the reception of the data at the raster module 3, then a corresponding status bit is set in the DMA controller 10 of the bus 15 controller 9 and the DMA controller ends the transfer on its own. When no immediate actions are triggered at the processor as a result thereof, then the following executive sequence derives:

An internal buffer of the raster module 3 for the reception of the data messages fills up. The raster module therefore rejects further data messages. The bus 20 controller of the I/O module repeats a rejected data message for a maximum of 127 times and then ends the data transfer on its own. The bus controller 9 of the I/O module subsequently reports the situation to its processor.

In addition, an internal fail-safe counter runs down at the raster module, this being always set to its start value by the reception of a data message. The 25 rundown of the counter is communicated to the processor of the raster module, which subsequently implements an error recovery known from the multibus.

In a preferred embodiment of the invention for accelerating the above executive sequence at the side of the raster module (the fail-safe counter runs down in approximately 2 seconds), the processor of the raster module can already react to the 30 DMA error in that it stops the DMA reception channel of the transfer and communicates the end of the transfer via an unsolicited message to the I/O module.

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The stopping ensues at the I/O module by an erase instruction output by the bus controller to erase the corresponding DMA reception channel.

When a DMA error occurs at the I/O module, the DMA channel is stopped by the internal executive sequencer -- as in the case of an error at the raster module --

and the corresponding status bits are set. Additionally, an unsolicited message is sent to the raster module, so that this stops the reception of the data message. Due to this message, the processor of the raster module forwards a stop instruction to the DMA controller and an erase instruction to the reception channel of the automatically requested message transfer. When the processor of the I/O module does not react to

the DMA error, then the aforementioned fail-safe counter on the raster module runs down. Subsequently, the processor of the raster module must send an unsolicited message to the I/O module, so that the I/O module also ends the transfer.

The aforementioned fail-safe counter of the raster module is provided for the reception of the data messages and is restarted every time after the reception of a

data message of the type 3CH. It runs down when no further data message is received within the time that has been set. In this case, the processor of the raster module stops the DMA channel in the bus controller and the reception channel of the automatically requested message transfer is erased. Additionally, an unsolicited message is sent to the I/O module so that the I/O module can stop the automatic requested message

transfer. A stop instruction for the DMA channel of the I/o module is thereby not necessary since this is undertaken by the internal executive sequences of the bus controller.

A running, automatic requested message transfer at the raster module can be aborted with an erase instruction at the corresponding reception channel. The instruction takes immediate effect. All data messages arriving thereafter are rejected by the bus controller with an error message “transfer not understood” that is known from the multibus. The termination of the reception channel of the DMA controller must likewise be implemented by the processor.

A running, automatic requested message transfer is aborted or,

respectively, arrested at the I/o module as a result of the following actions:

a) An error has occurred at the databus. All errors come into consideration:

- The repetition rate for a data message has reached the maximum value.
  - a bus error, bus timeout or an agent error occurred in the transmission of the data message.
- 5 b) An error occurred in the DMA transmission. The following errors come into consideration:
- parity error
  - page miss error
  - fatal error given a transfer via the internal computer bus (PCI bus).
- 10 c) The processor aborts the running, automatic requested message transfer with a command.
- In cases a0 and b), the automatic, requested message transfer is aborted by the internal controller of the bus controller due to the error. The internal controller reports the cause of the error by setting an ASOMERR bit in a message status register.
- 15 When a corresponding interrupt is enabled in a message control register, then an interrupt is additionally generated. The processor of the I/O module can determine the cause of the error by reading out an ASOM status register allocated to the automatic, requested message transfer. Before an automatic, requested message transfer can be resumed, the processor of the I/O module must output a corresponding command (ASOMGO).
- 20 The processor cannot abort an running, automatic requested message transfer at any time (see c). Dependent on the command employed, the automatic requested message transfer is still completely implemented or is immediately interrupted. It must be taken into consideration in the latter case that the raster module is waiting for the further arrival of data messages. A corresponding message is therefore sent from the I/O module to the raster module given an interruption of an automatically requested message transfer.
- 25 For logging the automatic requested message transfer, the following options can be established at the I/O module:

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1. Each automatic requested message transfer is forwarded to the processor of the I/O module. Which assembly requested an automatic requested message transfer can thus be kept track of on the I/O module.
2. A register is provided in the bus controller that contains the message ID of the assembly requesting the automatic requested message transfer. This register is set to the message ID at the beginning of the transfer and is in turn reset at the end. The register can be read out at any time by the processor.

5 The invention has been set forth above on the basis of a control device for editing print data for a high-performance printer. The inventive control device is equally suited for any application wherein a large data stream must be processed. The I/O module, accordingly, can be considered in general as a transmitter assembly and the raster module can be considered as a receiver module, whereby the data are transmitted from the transmitter module to the receiver module.

10 15 In the above-described exemplary embodiment, a databus is employed that is essentially compatible with the multibus. The invention, however, is not limited to this type of databus but can be designed for any parallel databus that is suitable for a multi-processor architecture.

20 A DMA controller 10 integrated into the bus controller 9 is provided in the assemblies recited in the exemplary embodiment.

In the framework of the invention, of course, the DMA controller 10 can also be arranged outside the bus controller 9 on the assembly.

25 The above-described data messages respectively transmit a data packet of 32 bytes. The size of these data packets can be varied as needed and, for example, comprise 64 or 128 bytes. The data quantity transferred with an automatic requested message transfer can be fixed to any desired size of, for example, 4 KB, 8 KB, 16 KB or the like.

The invention can be summarized in brief in the following way:  
It is directed to an electronic control device with a parallel databus and a plurality of  
30 assemblies connected to the databus. The assemblies respectively comprise a processor and a memory device and are connected to the databus with a bus

controller. The data are transmitted between a transmitter assembly and a receiver assembly with messages. The data bus essentially corresponds to the MULTIBUS II.

The invention is characterized in that the bus controller of the transmitter assembly is fashioned such that, without making use of the processor of the transmitter assembly, it reads data stored in the memory device of the transmitter assembly in response to a request message of the receiver assembly and sends them to the receiver assembly.

As a result thereof, first, the processor of the transmitter assembly (I/O module) is relieved and, second, the communication between the transmitter assembly and the receiver assembly (raster module) can be significantly lowered and reduced to a single request message in the negotiation or, respectively, determination of the data transfer. The electronic control device is preferably fashioned for a control device for driving a high-performance printer.

卷之三

## List of Reference Characters

- 1. electronic control device
  - 2. I/O module
  - 3. raster module
  - 5 4. serializer module
  - 5. databus
  - 6. pixel bus
  - 7. high-performance printer
  - 8. assembly
  - 10 9. bus controller
  - 10. DMA controller
  - 11. processor
  - 12. memory device
  - 13. internal computer bus

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### **Claims**

1. Electronic control device with a parallel databus (5) and a plurality of assemblies (8) connected to the databus (5) that respectively comprise a processor (11), a memory device (12) and a DMA controller (10) and that are connected to the databus (5) with a bus controller (9), whereby data are transmitted between a transmitter assembly and a receiver assembly with messages, whereby the bus controller (9) of the transmitter assembly is fashioned such that, in response to a request message of the receiver assembly, it programs the DMA controller to read out data stored in the memory device (12) of the transmitter assembly and to send them to the transmitter assembly, without making use of the processor (11) of the transmitter assembly.
  2. Electronic control device according to claim 1, characterized in that the DMA controller (10) is integrated into the bus controller (9) of the transmitter assembly.
  3. Electronic control device according to claim 1 or 2, whereby the databus (5) is a data bus compatible with the MULTIBUS II.
  4. Electronic control device according to one of the claims 1 through 3, characterized in that the receiver assembly comprises a fail-safe counter for monitoring the message transfer that is restarted upon reception of a data message.
  5. Method for the operation of an electronic device, whereby the electronic control device comprises a parallel databus (5) and a plurality of assemblies (2) connected to the databus that are respectively provided with a processor (11) and a memory device (12) and are connected to the databus (5) with a bus controller (9), whereby data are transmitted between a transmitter assembly and a receiver assembly with messages, and the receiver assembly initiates a data transfer by sending a request message to the transmitter module, and the bus controller (9) of the transmitter assembly, without making use of the processor of the transmitter assembly, transmits data stored in the memory device (12) of the transmitter assembly to the receiver assembly in response to the request message.
  6. Method according to claim 5, whereby a control device according to one of the claims 1 through 5 is employed.

7. Method according to claim 5 or 6, whereby, following the reception of a request message, the bus controller (9) of the transmitter assembly sends a plurality of data messages respectively containing a data packet to the receiver assembly.

8. Method according to one of the claims 5 through 7, whereby  
5 information for programming a DMA controller (10) arranged at the transmitter assembly for reading and sending the data stored in the memory device (12) of the transmitter assembly are transmitted with the request message .

9. Method according to one of the claims 5 through 8, whereby a DMA controller (10) arranged on the transmitter assembly is programmed by the bus  
10 controller (9) on the basis of data communicated with the request message, being program to read and transmit the data stored in the memory device (12) of the transmitter assembly.

10. Method according to one of the claims 5 through 9, whereby a DMA controller (10) arranged on the receiver assembly is programmed for the reception of  
15 the data with the transmission of the request message.

11. Method according to one of the claims 5 through 10, whereby the data are transmitted with a plurality of messages that respectively contain a data packet.

12. Method according to one of the claims 5 through 11, whereby the transmitter assembly comprises a buffer wherein an entry is provided for each  
20 assembly present in the control device, so that the parameters characterizing the data transfer are written into the respectively entry and stored during a data transfer and are erased after the conclusion of the data transfer.

13. Method according to claim 12, whereby, upon reception of a request message, the bus controller of the transmitter assembly checks whether the entry of  
25 the buffer allocated to the assembly sending the request message is already written with data characterizing a data transfer in order to prevent two data transfers from being simultaneously initiated with the same receiver assembly.

14. Control device for editing print data for a high-performance printer, comprising the features of one of the claims 1 through 5, whereby the transmitter  
30 assembly forms an I/O module (2) and a plurality of receiver modules that respectively form a raster module (3) are provided.

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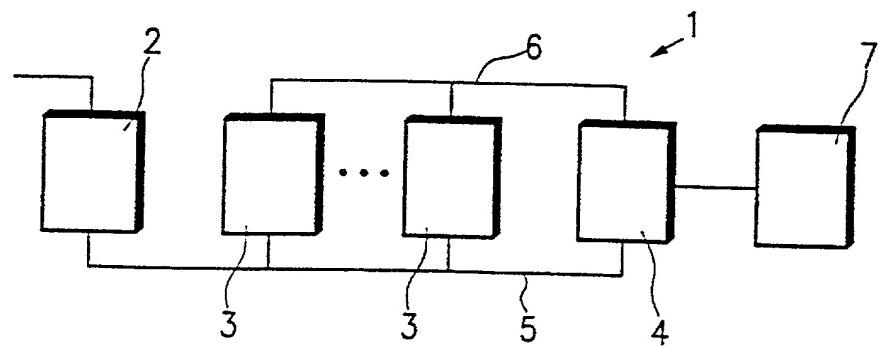


FIG.1

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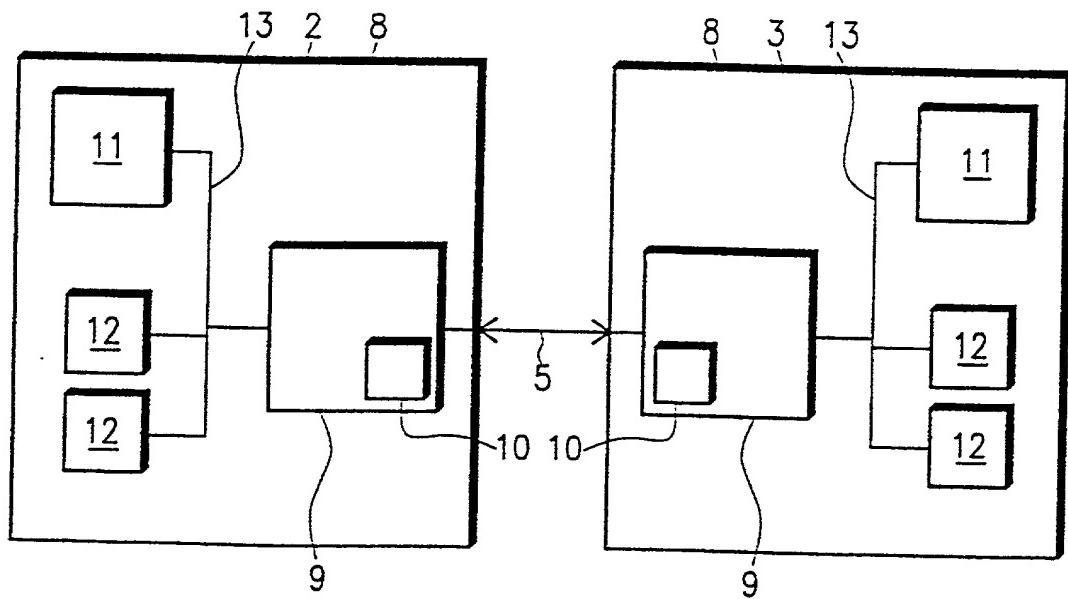


FIG.3

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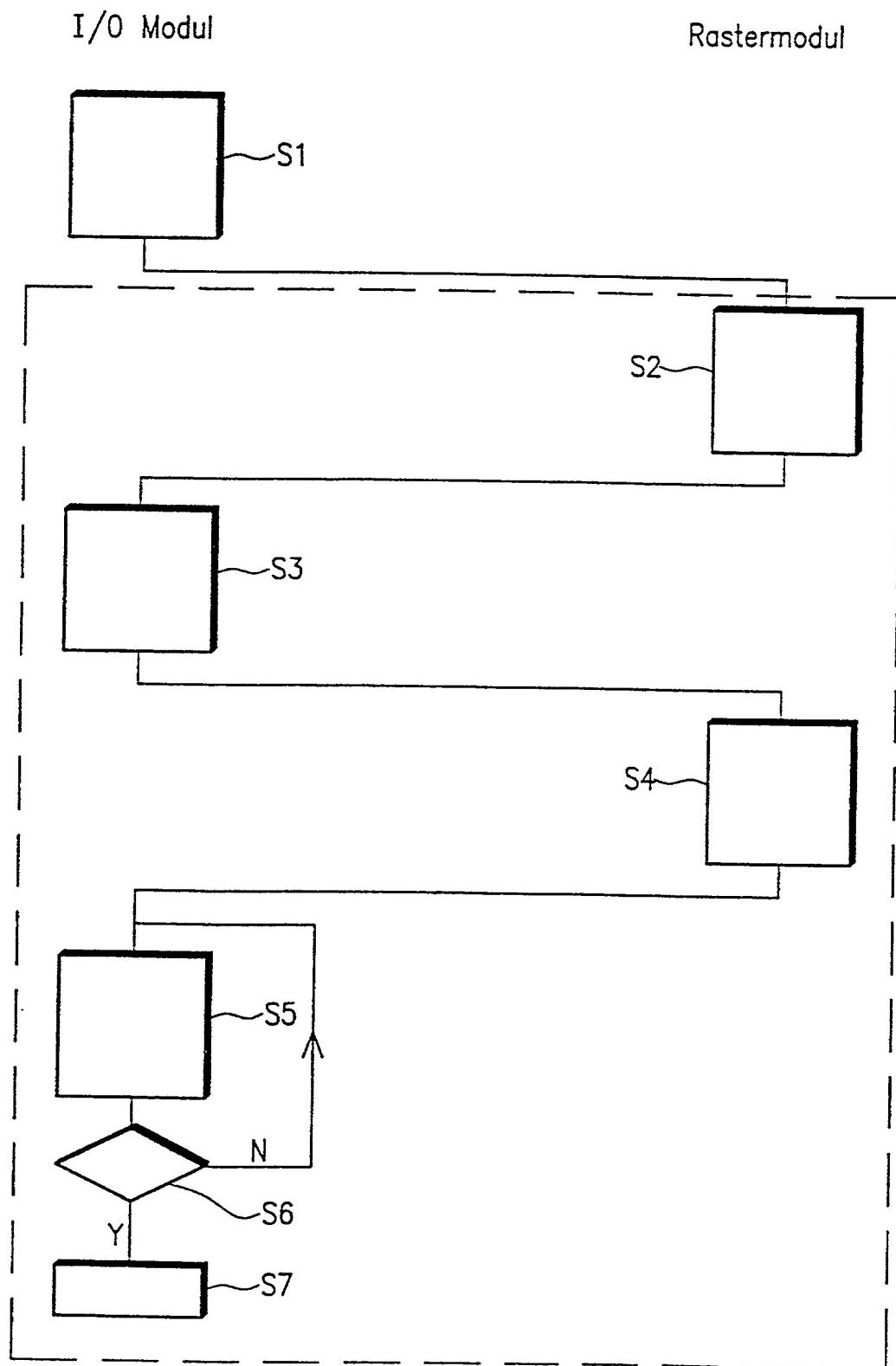


FIG. 2

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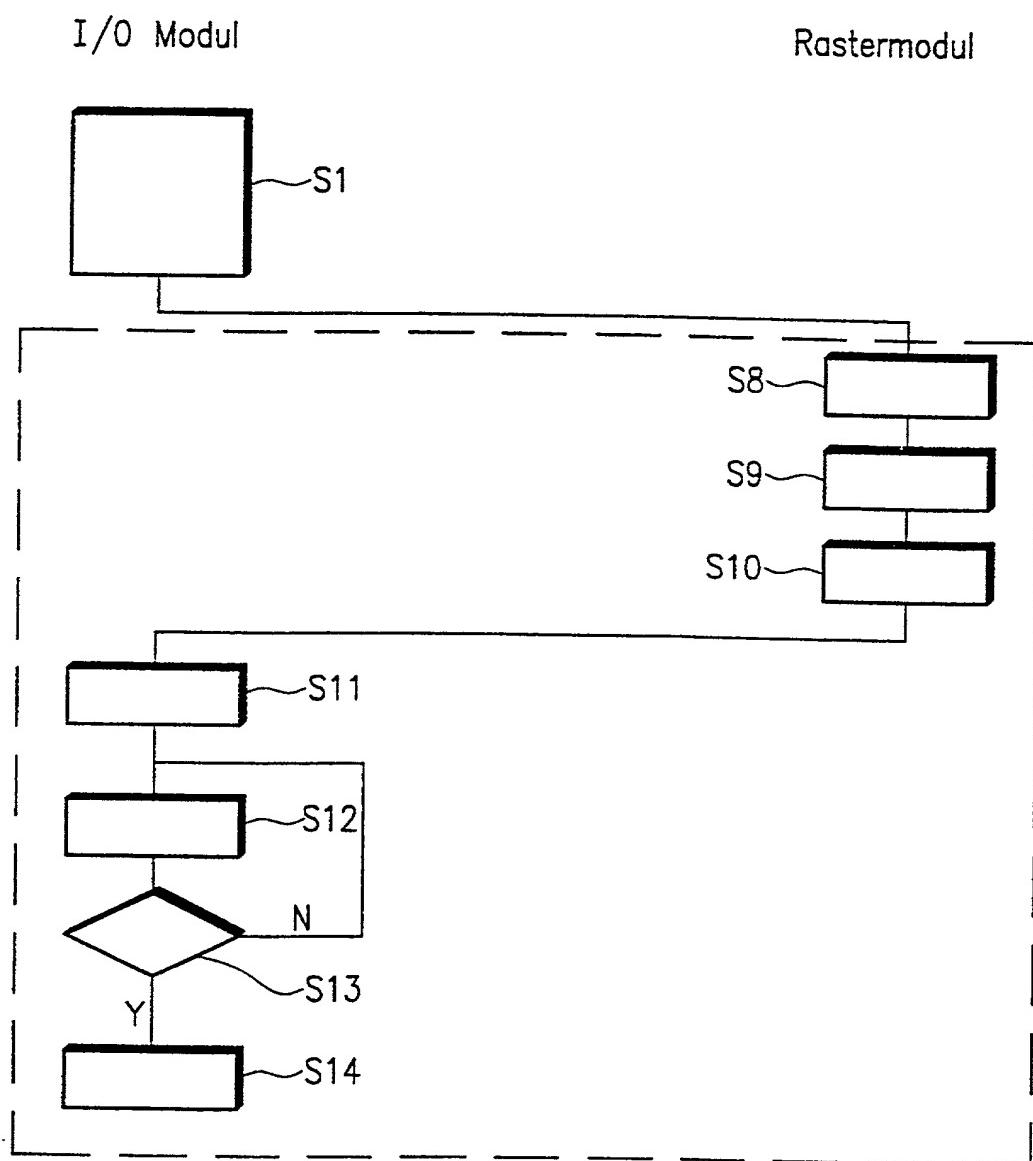


FIG.4

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D<31..24>	D<23..16>	D<15..8>	D<7..0>
Reserved	Type=02	Source_addr.	Dest_addr.
data addr. in I/O-CPU			
Duty Cycle	No. data bytes		"
Data byte 31	Data byte 30	Data byte 29	Data byte 28

FIG.5

D<31..24>	D<23..16>	D<15..8>	D<7..0>
		Source_addr.	Dest_addr.
Type=3CH,3DH			
Data byte 3	Data byte 2	Data byte 1	Data byte 0
"	Data		
Data byte 31	Data byte 30	Data byte 29	Data byte 28

FIG.6

	Byte 3	Byte 2	Byte 1	Byte 0
1		Duty Cycle	Source addr.	Destination addr.
2	DMA addr.			
3			Byte Count	

FIG.7

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**German Language Declaration**

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wird für die Erfindung mit dem Titel:

**ELEKTRONISCHE STEUEREINRICHTUNG MIT  
EINEM PARALLELEN DATENBUS UND  
VERFAHREN ZUM BETREIBEN DER  
STEUEREINRICHTUNG**

deren Beschreibung

(zutreffendes ankreuzen)

hier beigefügt ist.

am 12 October 1999 als  
PCT internationale Anmeldung  
PCT Anmeldungsnummer PCT/EP99/07631  
eingereicht wurde und am \_\_\_\_\_  
abgeändert wurde (falls tatsächlich abgeändert)

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Patentanmeldung einschließlich der Ansprüche  
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Bundesgesetzbuch, Paragraph 1.58(a) von Wichtigkeit  
sind, an.

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Auslandsanmeldungen für ein Patent oder eine  
Erfinderaukunde nachstehend gekennzeichnet, die ein  
Anmeldedatum haben, das vor dem Anmeldedatum  
der Anmeldung liegt, für die Priorität beansprucht wird.

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as stated below next to my name,

I believe I am the original, first and sole inventor (if only  
one name is listed below) or an original, first and joint  
inventor (if plural names are listed below) of the  
subject matter which is claimed and for which a patent  
is sought on the invention entitled

**ELECTRONIC CONTROL DEVICE COMPRISING A  
PARALLEL DATABUS, AND A METHOD FOR  
OPERATING THE CONTROL DEVICE**

the specification of which

(check one)

is attached hereto

was filed on        as  
PCT international application  
PCT Application No.                   
and was amended on                   
(if applicable)

I hereby state that I have reviewed and understand the  
contents of the above identified specification, including  
the claims as amended by any amendment referred to  
above.

I acknowledge the duty to disclose information which  
is material to the examination of this application in  
accordance with Title 37, Code of Federal Regulations,  
§1.58(a).

I hereby claim foreign priority benefits under Title 36,  
United States Code, §119 of any foreign application(s)  
for patent or inventor's certificate listed below and have  
also identified below any foreign application for patent  
or Inventor's certificate having a filing date before that  
of the application on which priority is claimed:

**German Language Declaration**

Prior foreign applications  
Priorität beansprucht

**Priority Claimed**

198 46 913.6 Germany  
(Number) (Country)  
(Nummer) (Land)

12 October 1998  
(Day Month Year Filed)  
(Tag Monat Jahr eingereicht)

Yes Ja  
 No Nein

\_\_\_\_\_ (Number)  
\_\_\_\_\_ (Country)  
\_\_\_\_\_ (Nummer) \_\_\_\_\_ (Land)

\_\_\_\_\_ (Day Month Year Filed)  
\_\_\_\_\_ (Tag Monat Jahr eingereicht)

Yes Ja  
 No Nein

Ich beanspruche hiermit gemäss Absatz 35 der Zivilprozeßordnung der Vereinigten Staaten, Paragraph 120, den Vorzug aller unten aufgeführten Anmeldungen und falls der Gegenstand aus jedem Anspruch dieser Anmeldung nicht in einer früheren amerikanischen Patentanmeldung laut dem ersten Paragraphen des Absatzes 35 der Zivilprozeßordnung der Vereinigten Staaten, Paragraph 122 offenbart ist, erkenne ich gemäss Absatz 37, Bundesgesetzbuch, Paragraph 1.56(a) meine Pflicht zur Offenbarung von Informationen an, die zwischen dem Anmeldedatum der früheren Anmeldung und dem nationalen oder PCT internationalen Anmeldedatum dieser Anmeldung bekannt geworden sind.

I hereby claim the benefit under Title 35, United States Code, §120 of any United States application(s) listed below and, insofar as the subject matter of each of the claims of this application is not disclosed in the prior United States application in the manner provided by the first paragraph of Title 35, United States Code, §122 I acknowledge the duty to disclose material information as defined in Title 37, Code of Federal Regulations, §1.56(a) which occurred between the filing date of the prior application and the national or PCT international filing date of this application.

\_\_\_\_\_ (Application Serial No.)  
\_\_\_\_\_ (Anmeldeseriennummer)

\_\_\_\_\_ (Filing Date)  
\_\_\_\_\_ (Anmeldedatum)

\_\_\_\_\_ (Status)  
(patentiert,anhängig,  
aufgegeben)

\_\_\_\_\_ (Status)  
(patented,pending,  
abandoned)

\_\_\_\_\_ (Application Serial No.)  
\_\_\_\_\_ (Anmeldeseriennummer)

\_\_\_\_\_ (Filing Date)  
\_\_\_\_\_ (Anmeldedatum)

\_\_\_\_\_ (Status)  
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Patent Department  
**6800 Sears Tower, Chicago, Illinois 60606**  
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Voller Name des einzigen oder ursprünglichen Erfinders: <b>Hans-Detlef GROEGER</b>	Full name of sole or first inventor.
Unterschrift des Erfinders <b>16 Detlef Groeger</b>	Date <b>11.04.01</b>
Wohnort <b>Poing, Germany</b>	Residence <b>DEX</b>
Staatsangehörigkeit <b>German</b>	Citizenship
Postanschrift <b>Anton-Zwengauer-Weg 1</b>	Post Office Address
<b>D-85586 Poing, GERMANY</b>	

(Bitte entsprechende Informationen und Unterschriften im Falle von weiteren Miterfindern angeben).

(Supply similar information and signature for subsequent joint inventors).

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Unterschrift des Erfinders <i>Robert Baumgartner</i>	Datum 11.04.01	Inventor's signature	Date
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Staatsangehörigkeit German		Citizenship	
Postanschrift Grafenwerderstrasse 4		Post Office Address	
D-85457 Wörth, Germany			
Voller Name des dritten Miterfinders (falls zutreffend):		Full name of third joint inventor, if any:	
Unterschrift des Erfinders	Datum	Inventor's signature	Date
Wehnsitz		Residence	
Staatsangehörigkeit		Citizenship	
Postanschrift		Post Office Address	
Voller Name des vierten Miterfinders (falls zutreffend):		Full name of fourth joint inventor, if any:	
Unterschrift des Erfinders	Datum	Inventor's signature	Date
Wehnsitz		Residence	
Staatsangehörigkeit		Citizenship	
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